

# **B3S & B3W ELECTRIC RODLESS ACTUATORS**



# Tolomatic B3S & B3W Electric Rodless Actuators A belgium



### The Power to Move Heavy Loads

The B3S and B3W electric rodless actuators have very large moment and load carrying capacities. The sealed recirculating ball bearing design makes it an excellent choice for challenging environments. For even higher capacity (loads up to 3,629 kg.) choose the Dual 180° Carrier and add an auxiliary carrier. Both actuators utilize a patented internal re-circulating ball bearing guidance system that provides extremely long life. These actuators are capable of carrying loads up to 3,629 kg [8,000 lbs].

### A COMPARISON OF SCREW DRIVE ACTUATORS

	TRS	B3S	MXE-S	MXE-P
		G	0 %	
Features:	Dual profile rail bearing actuator	High load and bending moment capacities	Basic guidance and support	High load and bending moment capacities
Load up to: (with options)	6.0 kN [1,356 lbf]	35.6 kN [8,000 lbf]	4.6 kN [1,040 lbf]	11.5 kN [2,584 lbf]
Thrust up to:	2.5 kN [562 lbf]	12 kN [2,700 lbf]	19.1 kN [4,300 lbf]	19.1 kN [4,300 lbf]
Speed up to:	0.91 m/sec [36 in/sec]	1.5 m/sec [60 in/sec]	1.5 m/sec [60 in/sec]	1.5 m/sec [60 in/sec]
Stroke Length up to:	1.1 m [43 in]	4.5 m [179 in]	4.5 m [178 in]	4.5m [178 in]
Screw/Nut Type	Solid & Ball	Solid & Ball	Solid & Ball	Solid & Ball
	www.tolor	natic.com for complete inf	ormation, search by literatu	ire number:
Literature Number:	3600-4222	3600-4176	8300-4000	8300-4000

(Not all models deliver ALL maximum values listed, i.e.: Maximum thrust may not be available with maximum speed)

### A COMPARISON OF BELT DRIVE ACTUATORS

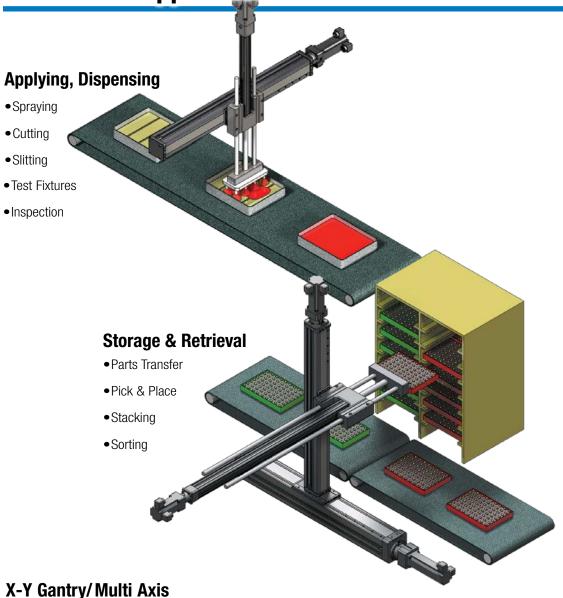
	B3W	MXB-U	MXB-S	MXB-P
Features:	High load and bending moment capacities	Basic thrust, requires exter- nal guidance and support	Medium load and bending moment capacities	High load and bending moment capacities
Load up to: (with options)	35.6 kN [8,000 lbf]	NA	4.6 kN [1,040 lbf]	11.5 kN [2,584 lbf]
Thrust up to:	1.4 kN [325 lbf]	1.9 kN [418 lbf]	1.9 kN [418 lbf]	1.9 kN [418 lbf]
Speed up to:	5.1 m/sec [200 in/sec]	5.1 m/sec [200 in sec]	2.5 m/sec [100 in sec]	3.9 m/sec [150 in/sec]
Stroke Length up to:	14.6 m [574 in]	10.5 m [414 in]	10.5 m [414 in]	10.5 m [414 in]
	www.tolor	natic.com for complete inf	ormation, search by literatu	ire number:
Literature Number:	3600-4176	8500-4000	8500-4000	8500-4000
Stroke Length up to:	14.6 m [574 in] www.tolor 3600-4176	10.5 m [414 in]	10.5 m [414 in] ormation, search by literatu 8500-4000	10.5 m [414 in] are number: 8500-4000

(Not all models deliver ALL maximum values listed, i.e.: Maximum thrust may not be available with maximum speed)



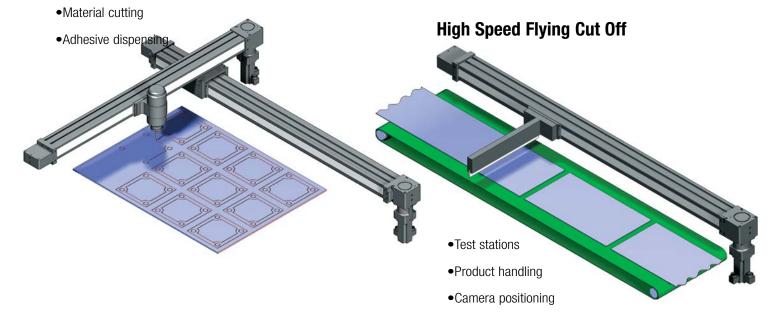
# LDA belgium

**B3S & B3W Applications** 



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### Laser marking



# **B3S RODLESS SCREW DRIVE ACTUATOR**

# **ENDURANCE TECHNOLOGY**

designed for maximum durability to provide extended service life.

The B3S rodless screw-drive electric actuator is designed for carrying moderate to heavy loads with large bending moment capacity. The B3S utilizes an integral recirculating ball bearing quidance system that provides durable performance and extremely long life. Choose from multiple screw technologies for thrust up 12 kN [2,700 lbf]. Built-to-order in stroke lengths up to 10.6 m [416 inches].

# **LOAD-BEARING CARRIER DESIGN** Load and moments are transmitted directly to the actuator body **FORMED END CAP WIPERS** Prevent contaminants from entering the sealing band area to

### **SCREW SUPPORT BEARINGS**

Unique high thrust bearing assembly design eliminates runout and isolates the linear forces from the drive shaft

### **MOTOR ORIENTATION**

Tolomatic...MAXIMUM DURABLETUM

### YOU CAN CHOOSE:

- •Inline option directly couples the driving shaft and is typically a onepiece housing construction for optimum alignment and support of the motor
- Reverse-parallel option minimizes the overall length and offers a belt reduction drive with a 1:1 or 2:1 ratio

### **YOUR MOTOR HERE**

### YOU CAN CHOOSE:

- •Specify the device to be installed and actuator ships with proper mounting hardware
- •Specify and ship your device to Tolomatic for factory installation
- Motor or gearbox supplied and installed by Tolomatic

### LIGHTWEIGHT ALUMINUM DESIGN

- •Black anodized extrusion design is optimized for rigidity and strength
- •External switch channels on both sides allow easy placement and adjustment of position indicating switches

### **OPTIONS**

### **CARRIER OPTIONS**

- AUXILIARY CARRIER doubles the load capacity and increases pitch and yaw bending moment
- DUAL 180° CARRIER doubles the load capacity, increases roll and yaw bending moment capacities and offers a wide mounting platform

### **MOUNTING OPTIONS**

- SURFACE MOUNT two t-slots are integral on the entire underside of the actuator body for direct mounting
- •TUBE SUPPORTS provide intermediate support of the actuator body throughout long stroke lengths
- MOUNTING PLATES provide intermediate support of the actuator body throughout long stroke lengths

### •METRIC OPTION

Provides metric tapped holes for mounting of load to carrier and of actuator to mating surfaces



### • SWITCHES

Styles include: reed, hall-effect or triac. Select either 5 m potted cable with flying leads or 150 mm to guickdisconnect coupler with mating 5 m cable

### YOU CAN CHOOSE:

- Solid nuts of engineered resins offer quiet performance at the lowest cost; anti-backlash available
- Ball nuts offer positioning accuracy and repeatability with longer life: lowbacklash available







### **INTERNAL BUMPERS**

Bumpers protect the screw and nut assembly from damage at end of stroke

protect internal components

### STAINLESS STEEL SEALING BAND

- Prevents contaminants from entering the screw and nut area for extended performance
- Fatigue resistant stainless steel bands are specifically made to offer long life and will not elongate
- Provides IP44 protection for bearings and screw nut

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### **MULTIPLE SCREW TECHNOLOGIES**



 Unique design incorporates hardened steel raceways integral to the aluminum extrusion

RECIRCULATING BALL BEARING SYSTEM

- Bearing surfaces are adjusted at the factory for optimum preload and smooth performance
- Recirculating ball bearing system provides guidance, high efficiency and durability

**Tolomatic** 



# **B3W RODLESS BELT-DRIVE ACTUATOR**

# ENDURANCE TECHNOLOGY Leadures are designed for maximum durability to provide extended service life.

The B3W rodless belt-drive electric actuator is designed for carrying moderate to heavy loads at moderate to high speeds with large bending moment capacity. The B3W utilizes an integral recirculating ball bearing guidance system that provides durable performance and extremely long life. The B3W belt-driven actuator features speeds up to 5.1 m/ sec [200 in/sec]. Built-to-order in stroke lengths up to 5.3 m [207 inches]

### YOUR MOTOR HERE

### YOU CAN CHOOSE:

- •Specify the device to be installed and actuator ships with proper mounting hardware
- •Specify and ship your device to Tolomatic for factory installation
- Motor or gearbox supplied and installed by Tolomatic

### STAINLESS STEEL SEALING BAND

- Prevents contaminants from entering the screw and nut area for extended performance
- Fatique resistant stainless steel bands are specifically made to offer long life and will not elongate
- Provides IP44 protection for bearings and screw nut

**LOAD-BEARING** 

**CARRIER DESIGN** 

Load and moments are transmitted

directly to the

actuator body

FORMED END CAP

**WIPERS** 

contaminants

from entering

the sealing

band area to

components

protect internal

Prevent

RECIRCULATING BALL BEARING SYSTEM

Unique design incorporates hardened steel

raceways integral to the aluminum extrusion

• Bearing surfaces are adjusted at the

factory for optimum preload and smooth

• Recirculating ball bearing system provides

guidance, high efficiency and durability

# Tolomatic...MAXIMUM DURABEIRIUM

### **BELT TENSIONING SYSTEM**

- Full access to the idle pulley allows ease of adjustment for alignment and tensioning
- Dual adjustment screws and field tensioning kit provide simple maintenance



### **MOTOR ORIENTATION**

### YOU CAN CHOOSE:

- Direct drive option directly couples the driving shaft and is typically a one-piece housing construction for optimum alignment and support of the motor
- •Reduction drive option minimizes the overall length and offers a belt reduction drive with a 1:1 or 2:1 ratio

### **LIGHTWEIGHT ALUMINUM DESIGN**

- •Black anodized extrusion design is optimized for rigidity and strength
- •External switch channels on both sides allow easy placement and adjustment of position indicating switches

### INTERNAL **BUMPERS**

Bumpers protect the screw and nut assembly from damage at end of stroke

### MULTIPLE BELT TECHNOLOGIES

•Polyurethane Kevlar reinforced HTD style belt

### **OPTIONS**

### **CARRIER OPTIONS**

- AUXILIARY CARRIER doubles the load capacity and increases pitch and yaw bending moment
- DUAL 180° CARRIER doubles the load capacity, increases roll and yaw bending moment capacities and offers a wide mounting platform



- SURFACE MOUNT two t-slots are integral on the entire underside of the actuator body for direct mounting
- •TUBE SUPPORTS provide intermediate support of the actuator body throughout long stroke lengths
- MOUNTING PLATES provide intermediate support of the actuator body throughout long stroke lengths

### METRIC OPTION

Provides metric tapped holes for mounting of load to carrier and of actuator to mating surfaces



### • SWITCHES

Styles include: reed, hall-effect or triac. Select either 5 m potted cable with flying leads or 150 mm to guickdisconnect coupler with mating 5 m cable

### **OVERSIZED PULLEY BEARINGS**

Drive shaft assembly incorporates sealed ball bearings for complete support of the increased belt tension at high speeds

### YOU CAN CHOOSE:

 Polyurethane steel-cord reinforced HTD style belt (standard)





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### **B3S & B3W Electric Rodless Actuators**

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### **SPECIFICATIONS both Screw & Belt Drive**

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				METRIC		U.S. (	ONVENTI	ONAL
SINGLE (STANDARD) CARRIER		Size	10	15	20	10	15	20
Fz <b>1</b>	Mx Moment (Roll)	(N-m : lb-in)	28.2	97	188	250	859	1,662
Fy Mz	My Moment (Pitch)	(N-m : lb-in)	30.4	117	166	269	1,033	1,472
My	Mz Moment (Yaw)	(N-m : lb-in)	17.6	67	96	156	596	850
Mx	Fy Load (Radial)	(N : lb)	1,517	3,737	5,155	341	840	1,159
	Fz Load (Lateral)	(N : lb)	2,629	6,468	8,932	591	1454	2008
AUXILIARY CARRIER: Increases rigidity, load-ca	arrying capacity and m	oments Size	10	15	20	10	15	20
Fz <b>1</b>	Mx Moment (Roll)	*(N-m : lb-in)	57	194	376	500	1,718	3,324
Fy Mz	My Moment (Pitch)	*(N-m : lb-in)	319	1,326	1,838	2,825	11,734	16,265
My	Mz Moment (Yaw)	*(N-m : lb-in)	184	766	1,061	1,630	6,779	9,388
Mx Z	Fy Load (Radial)	(N : lb)	3,034	7,473	10,311	682	1,680	2,318
"b"	Fz Load (Lateral)	(N : lb)	5,258	12,935	17,864	1,182	2,908	4,016
	Minimum Dimension	<b>n 'D'</b> (mm : in)	124	205	206	4.88	8.07	8.10
DUAL 180° CARRIER: Allows 90° rotation of load	l, adds load bearing su	rface Size	10	15	20	10	15	20
Fz <b>↑</b>	Mx Moment (Roll)	(N-m : lb-in)	74	279	512	657	2,468	4,527
Fy Mz	My Moment (Pitch)	(N-m : lb-in)	35.3	135	192	312	1,192	1,700
My	Mz Moment (Yaw)	(N-m : lb-in)	61	233	333	538	2,066	2,944
Mx 7	Fy Load (Radial)	(N : lb)	5,258	12,935	17,864	1,182	2,908	4,016
	Fz Load (Lateral)	(N : lb)	3,034	7,473	10,311	682	1,680	2,318
AUXILIARY DUAL 180° CARRIER: Substantially i	ncreases moment and	loads Size	10	15	20	10	15	20
Fz ‡	Mx Moment (Roll)	* (N-m : lb-in)	149	558	1,023	1,314	4,936	9,054
Fy Mz	My Moment (Pitch)	* (N-m : lb-in)	376	1,532	2,121	3,328	13,558	18,776
MX 7	Mz Moment (Yaw)	* (N-m : lb-in)	652	2,652	3,675	5,768	23,468	32,530
U	Fy Load (Radial)	(N : lb)	10,516	25,871	35,728	2,364	5,816	8,032
	Fz Load (Lateral)	(N : Ib)	6,067	14,946	20,622	1,364	3,360	4,636
	Minimum Dimension	<b>n 'D'</b> (mm : in)	124	205	206	4.88	8.07	8.10



The Dual 180° carrier requires its own proprietary tube supports and foot mounts. See dimensional information. Breakaway torque will also increase when using the Auxiliary carrier or the Dual 180° carrier options. When ordering, determine working stroke and enter this value into the configuration string. Overall actuator length will automatically be calculated.

Deflection Considerations: In applications where substantial Mx or My moments come into play, deflection of the cylinder tube, carrier and supports must be considered. The deflection factors shown in the Load Deflection charts on the following page are based on cylinder mounted with tube supports at minimum recommended spacing. If more rigidity is desired, refer to the Auxiliary or Dual Carrier options.

\*Loads shown in table are at minimum "D" dimension, for ratings with longer "D" dimension see graphs on page B3\_10.

Life of the actuator will vary for each application depending on the combined loads, motion parameters and operating conditions. The load factor ( $L_F$ ) ratios for each application must not exceed a value of 1.5 (see formula at right). Exceeding a load factor of 1.5 will diminish the actuator's rated life.  $L_F = \frac{Mx}{Mx_{max}} + \frac{My}{My_{max}} + \frac{Mz}{Mz_{max}} + \frac{Fy}{Fy_{max}} + \frac{Fz}{Fz_{max}} \le 1.5$ 

With combined loads, L<sub>F</sub> must not exceed the value 1.5



### **B3S & B3W Electric Rodless Actuators**

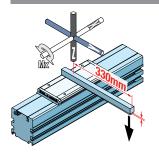
### **SPECIFICATIONS both Screw & Belt Drive**

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### **DEFLECTION ABOUT X AXIS**

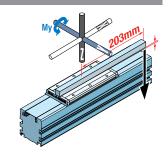
### **DEFLECTION ABOUT Y AXIS**



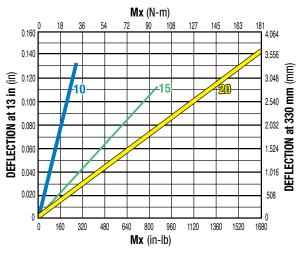
### 1.) Actuator was properly mounted with distance between supports within recommendations (see Support Recommendations below)

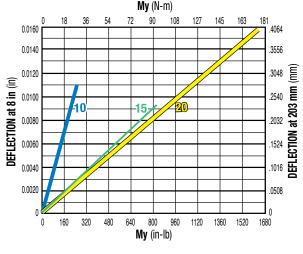
2.) Deflection was measured from center of carrier as shown (Mx = 330mm, My = 203mm)

**DEFLECTION TESTING WAS DONE UNDER THESE CRITERIA:** 



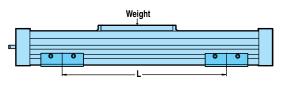
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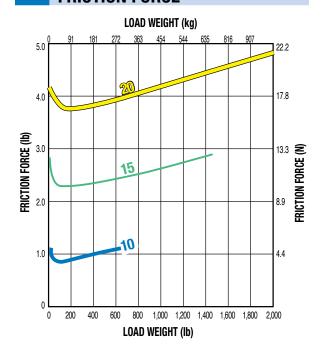


### SUPPORT RECOMMENDATIONS

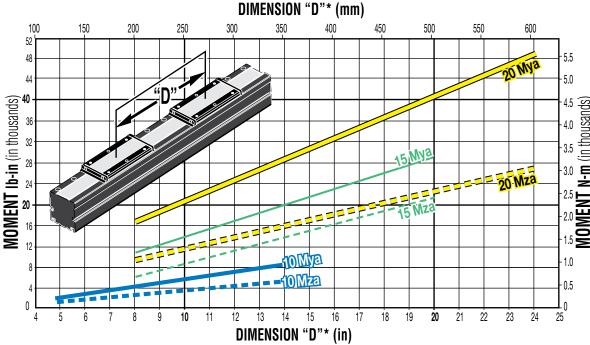
# MAX DISTANCE BETWEEN SUPPORTS (mm) "L" 2,100 MAXIMUM LOAD 1,500 MAXIMUM LOAD -7,000 -7,0



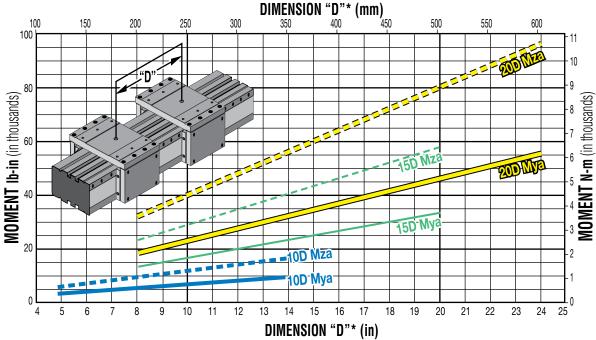
### FRICTION FORCE







### **AUXILIARY DUAL 180° CARRIER: BENDING MOMENT AT 'D' DISTANCE**



Rates shown on both graphs were calculated with these assumptions: 1.) Coupling between carriers is rigid.

- \* Customer must specify Dimension "D" (Distance between carrier center lines) when ordering.
- 2.) Load is equally distributed between carriers.
- 3.) Coupling device applies no misalignment loads to carriers.

Life of the actuator will vary for each application depending on the combined loads, motion parameters and operating conditions. The load factor ( $L_F$ ) ratios for each application must not exceed a value of 1.5 (see formula at right). Exceeding a load factor of 1.5 will diminish the actuator's rated life.  $L_F = \frac{Mx}{Mx_{max}} + \frac{My}{My_{max}} + \frac{Mz}{Mz_{max}} + \frac{Fy}{Fy_{max}} + \frac{Fz}{Fz_{max}} \le 1.5$ 

With combined loads, L<sub>F</sub> must not exceed the value 1.5

# B3S Electric Screw Drive Rodless Actuators LDA belgium

### **SPECIFICATIONS** Related to Actuator Size and Screw Selection

### **METRIC LEAD SCREWS**

B3S	MAX STROKE	SCREW	SCREW LEAD	MAX Thrust	LEAD Accuracy	BACKLASH	SCREW DIAMETER	BASE ACTUATOR INERTIA LMI	BASE ACTUATOR INERTIA RP	INERTIA PER mm OF STROKE	MAXIMUM DYNAMIC FRICTION TORQUE
SIZE	mm	TYPE	mm/rev	N	mm/300mm	mm	mm	kg-cm <sup>2</sup>	kg-cm <sup>2</sup>	kg-cm <sup>2</sup>	Nm
10	1,630	BNM10	10.00	1,832	0.10	0.06	10.0	0.010	0.012	0.0001	0.13
10	3,459	SN12	12.00	800	0.13	0.18	12.0	0.027	0.031	0.0001	0.20
15	3,388	BN(L)05	5.00	7,300	0.13	0.38	16.0	0.047	0.055	0.0005	0.27
15	3,388	SN12	12.00	900	0.13	0.18	15.0	0.141	0.162	0.0005	0.16
20	3,337	BN(L)05)	5.00	11,700	0.13	0.38	20.0	0.322	0.342	0.0011	0.25

<sup>(</sup>L) for low backlash ball screws: backlash = 0.05 mm

### **INCH (US Conventional) LEAD SCREWS**

B3S	MAX STROKE	SCREW	SCREW LEAD	MAX Thrust	LEAD ACCURACY	BACKLASH	SCREW DIAMETER	BASE ACTUATOR INERTIA LMI	BASE ACTUATOR INERTIA RP	INERTIA PER in OF STROKE	MAXIMUM Dynamic Friction Torque
SIZE	in	TYPE	turns/in	lbf	in/ft	in	in	lb-in <sup>2</sup>	lb-in <sup>2</sup>	lb-in <sup>2</sup>	lb-in
	64.2	BN(L)08	8.00	130	0.0040	0.015	0.375	0.003	0.004	0.0005	1.1
	136.2	SN05	5.00	170	0.0060	0.007	0.500	0.011	0.014	0.0017	1.3
10	134.2	SN02	2.00	170	0.0050	0.007	0.500	0.016	0.019	0.0017	1.8
	134.2	SNA02	2.00	170	0.0050	0.003	0.500	0.019	0.022	0.0017	1.8
	100.2	SN01	1.00	170	0.0060	0.007	0.500	0.032	0.035	0.0017	2.5
	61.4	BN(L)02	2.00	800	0.0030	0.015	0.500	0.025	0.028	0.0017	1.6
	61.4	BN(L)05	5.00	800	0.0030	0.015	0.625	0.040	0.047	0.0042	1.3
15	133.4	SN02	2.00	200	0.0050	0.007	0.625	0.048	0.055	0.0042	1.9
	133.4	SNA02	2.00	200	0.0050	0.003	0.625	0.048	0.055	0.0042	1.9
	133.4	SN01	1.00	300	0.0050	0.007	0.750	0.119	0.133	0.0087	2.8
20	131.4	BN(L)02	2.00	2,700	0.0040	0.015	0.750	0.116	0.122	0.0087	3.1
20	131.4	BN(L)05	5.00	950	0.0030	0.015	0.750	0.105	0.111	0.0087	2.2

<sup>(</sup>L) for low backlash ball screws: backlash = 0.0020"

### SCREW CODE DESCRIPTION

SN Solid Nut

SNA Anti-backlash Solid Nut

BN Ball Nut

BNL Low-Backlash Ball Nut

Contact Tolomatic for higher accuracy and lower backlash options.

For ball screws, maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.



<sup>\*</sup> For Acme screws, maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation.

### **B3S Electric Screw Drive Rodless Actuators**

# LDA belgium

### **SPECIFICATIONS**

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### **METRIC**

	WEI	GHT	WEIGHT PER	¹ STRAIGHTNESS &	<sup>2</sup> TEMPERATURE	
	CARRIER	BASE	UNIT OF STROKE	FLATNESS (supported)	RANGE	
	(kg)	(kg)	(g/mm)	(mm)	(°C)	<sup>3</sup> IP RATING
B3S10	0.40	1.00	5.40			
B3S15	0.70	3.96	10.18	0.00067 x L*	4 - 54	44
B3S20	0.97	6.52	15.73			

	WEI	GHT	WEIGHT PER
	CARRIER	BASE	UNIT OF STROKE
	(kg)	(kg)	(g/mm)
B3S10D	1.05	2.31	7.32
B3S15D	2.93	6.53	12.14
B3S20D	4.83	13.36	23.30



- ¹The listed values relating to straightness/flatness are intended for reference purposes only, and not as an engineering standard of absolute tolerance for a given actuator. Appropriate installation is the single most important factor in reducing such deviation, so good engineering practices such as measurement, mapping, etc. must be employed in applications with stringent straightness/flatness requirements.
- <sup>2</sup> Heat generated by the motor and drive should be taken into consideration as well as linear velocity and work cycle time. For applications that require operation outside of the recommended temperature range, contact the factory.

### **INCH (US Conventional)**

	WE	GHT	WEIGHT PER	<sup>1</sup> STRAIGHTNESS &	<sup>2</sup> TEMPERATURE	
	CARRIER	BASE	UNIT OF STROKE		RANGE	
	(lbs)	(lbs)	(lbs/in)	(in)	(°F)	<sup>3</sup> IP RATING
B3S10	0.85	2.15	0.30			
B3S15	1.56	8.75	0.57	0.00067 x L*	40 - 130	44
B3S20	2.15	14.38	0.88			

	WEI	GHT	WEIGHT PER
	CARRIER	BASE	UNIT OF STROKE
	(lbs)	(lbs)	(lbs/in)
B3S10D	2.32	5.10	0.41
B3S15D	6.47	14.40	0.68
B3S20D	10.65	29.45	1.31

- <sup>3</sup> Protected against ingress of solid particles greater than .039 in (1mm) and splashing water.
- \*"L" is maximum distance between supports— See the support recommendation graph on page B3\_9.

LARGE FRAME MOTORS AND SMALLER SIZE ACTUATORS: Cantilevered motors need to be supported, if subjected to continuous rapid reversing duty and/or under dynamic conditions.

### **LEAD SCREW EFFICIENCY**

SCREW/NUT		SIZE	
STYLE	10	15	20
Composite (ACME)	0.60		
Ball	0.90		
Ball Low Backlash	0.85		

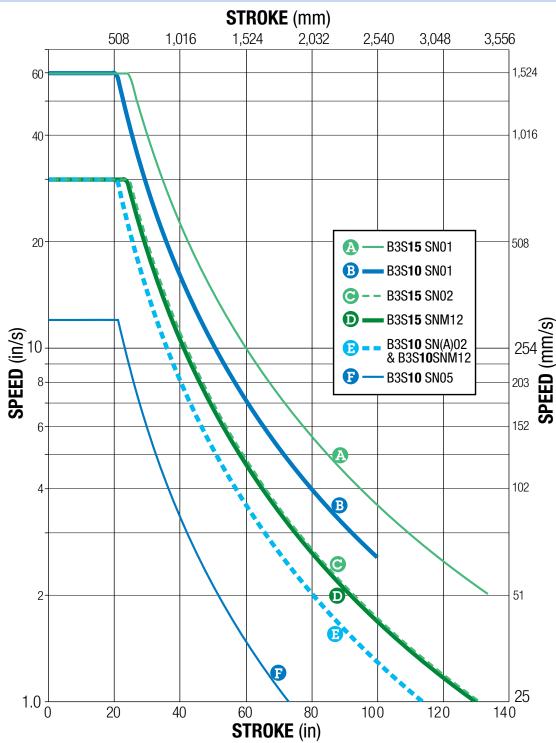


# B3S Electric Screw Drive Rodless Actuators LDA belgium

### **ACME SCREW/NUT COMBINATIONS**

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### **ACME SCREW CRITICAL SPEED CAPACITIES**





\* Maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity limitation.

Dotted lines represent maximum stroke for screw selections.

For Screw PV limits, refer to the individual charts located in the technical section for each actuator body size.

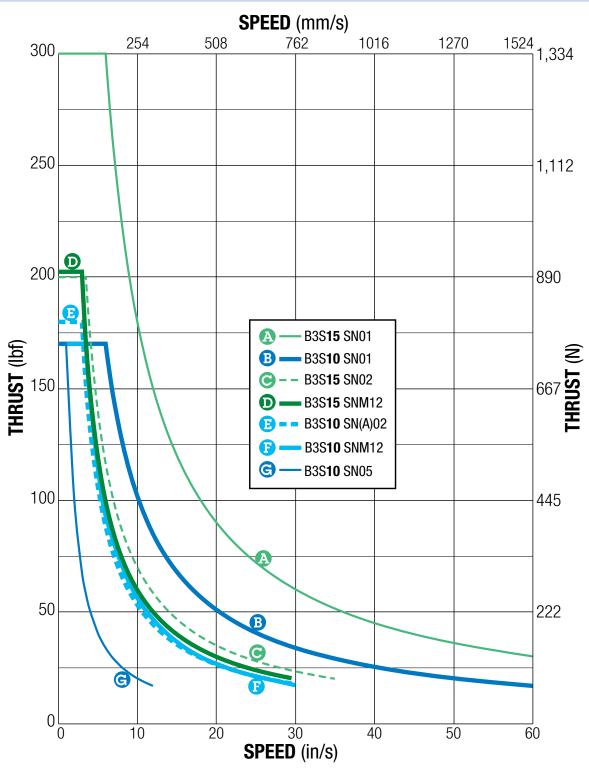
SCREW CODE DESCRIPTION **SNM Solid Nut SNA Anti-backlash Solid Nut** 



### **ACME SCREW/NUT COMBINATIONS**

sizeit.tolomatic.com for fast, accurate actuator selection

### **ACME SCREW PV LIMITS**



\* Maximum thrust is the maximum continuous dynamic thrust subject to Thrust x Velocity Limitation.

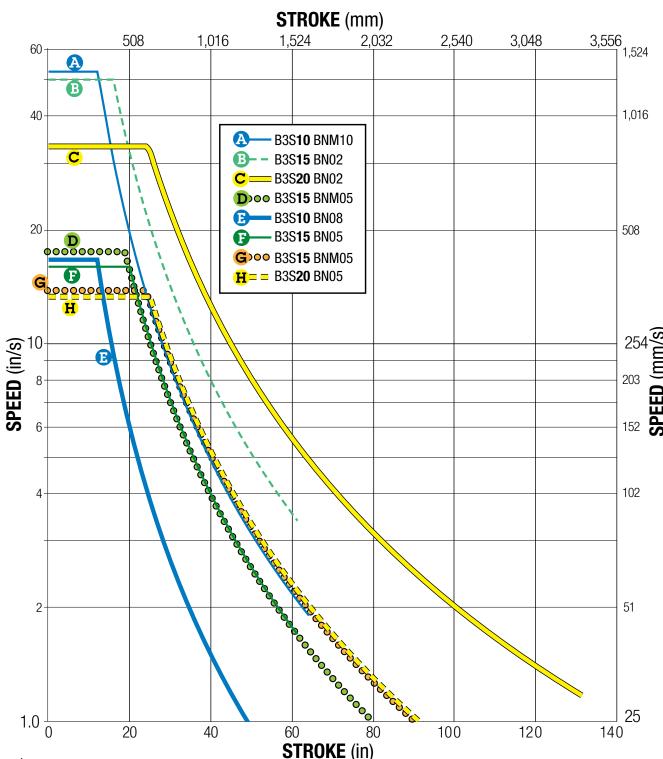
PV LIMITS: Any material which carries a sliding load is limited by heat buildup. The factors that affect heat generation rate in an application are the pressure on the nut in pounds per square inch and the surface velocity in feet per minute. The product of these factors provides a measure of the severity of an application.

# B3S Electric Screw Drive Rodless Actuators LDA belgium

### **BALL SCREW/NUT COMBINATIONS**

sizeit.tolomatic.com for fast. accurate actuator selection

### **BALL SCREW CRITICAL SPEED CAPACITIES**





\* Maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.

Dotted lines represent maximum stroke for screw selections.

SCREW CODE DESCRIPTION BN/BNM **Ball Nut** 

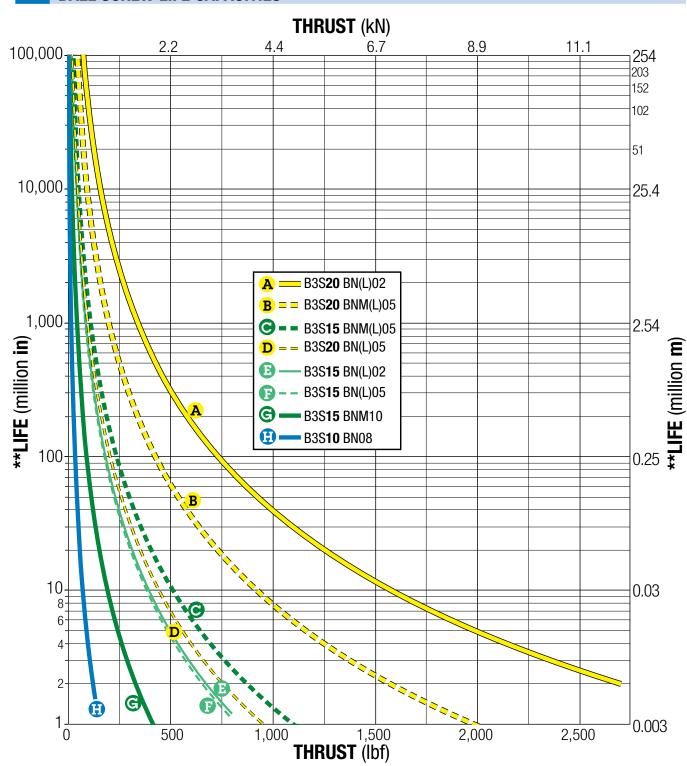
BNL/BNML Low-Backlash Ball Nut



sizeit.tolomatic.com for fast. accurate actuator selection

### **BALL SCREW/NUT COMBINATIONS**

### **BALL SCREW LIFE CAPACITIES**



\* Maximum thrust reflects 90% reliability for 25 million linear millimeters of travel.

Dotted lines represent maximum thrust for screw selections.

\*\*Life indicates theoretical maximum life of screw only, under ideal conditions and does not indicate expected life of actuator.



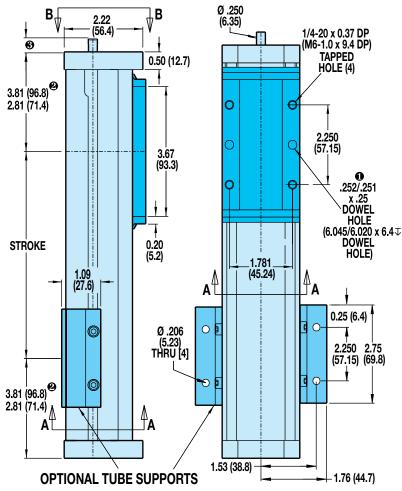


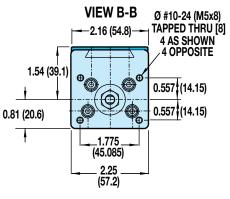
# B3S10 Electric Screw Drive Rodless Actuators DA belgium

### **DIMENSIONS Actuator & Options**

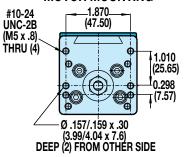
3D CAD available at www.tolomatic.com Always use configurated CAD solid model

to determine critical dimensions

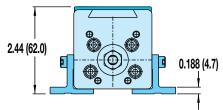




### **MOTOR MOUNTING**



### OPTIONAL TUBE SUPPORTS



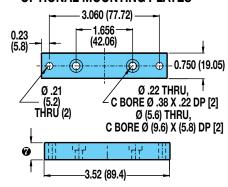
### SILVER NUTS FOR **SLOTS 90° FROM CARRIER** #3410-1013 [4410-1013]

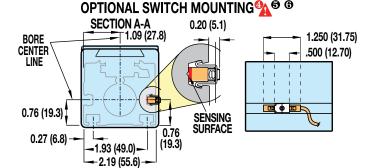
Ø#10-24 (M5-0.8) 0.35 (8.9) TAPPED HOLE (CENTERED) 0.66 (16.8) 0.25 (6.4)

### YELLOW NUTS FOR SLOTS OPPOSITE CARRIER #3410-1775 [4410-1708]

Ø#10-24 (M5-0.8) TAPPED HOLE 0.37 (9.4) (CENTERED) 0.75 (19.1) 0.188 (4.8)

### OPTIONAL MOUNTING PLATES





- **DOWEL PINS** | **●** | .003 (08mm) | **M**
- FOR SNA02 STYLE ONLY
- **SHAFT LENGTH** 0.55 (13.8) In-line mounting Extended shaft for RP & 23-frame motor 1.99 (50.5) Extended shaft for RP & 34-frame motor 2.20 (55.9) Extended shaft for purchases prior to 6/24/02 1.63 (41.4)

### CAUTION: DO NOT OVERTIGHTEN SWITCH HARDWARE WHEN INSTALLING

- **6** NOTE: The scored face of the switch indicates the sensing surface and must face toward the magnet
- NOTE: Some actuators require switch mounting on a specific side of the actuator. Call Tolomatic 1-800-328-2174 for details
- LMI with MRS is 1" (25.4mm) thick LMI with all others is 1/2" (12.7mm) thick RP, (YMH) all motors is 1/2" (12.7mm) thick

Unless otherwise noted, all dimensions shown are in inches (Dimensions in parenthesis are in millimeters)

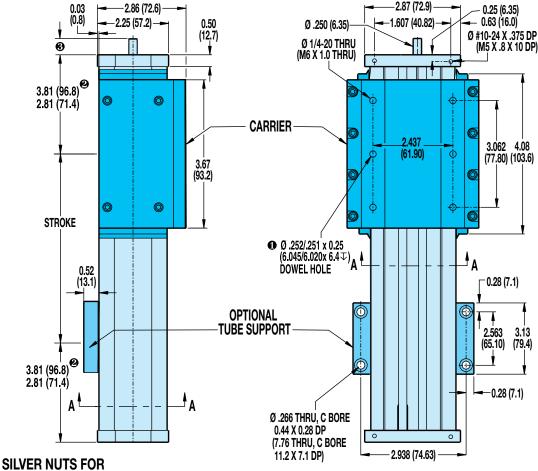


# B3S10 Electric Screw Drive Rodless Actuators DA belgium

### **DIMENSIONS Dual 180° Option**

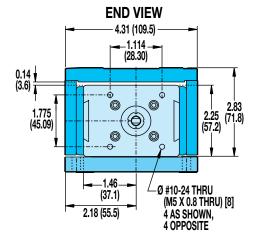
**3D CAD available at www.tolomatic.com**Always use configurated CAD solid model

to determine critical dimensions



SILVER NUTS FOR SLOTS 90° FROM CARRIER #3410-1013 [4410-1013]

# OPTIONAL SWITCH MOUNTING SECTION A-A 0.20 (5.1) SENSING SURFACE 0.76 (19.3) 1.250 (31.75) 500 (12.70) 0.76 (19.3)



B SHAFT I FNGTH

S SHALL LENGTH	
In-line mounting	0.55 (13.8)
Extended shaft for RP & 23-frame motor	1.99 (50.5)
Extended shaft for RP & 34-frame motor	2.20 (55.9)
Extended shaft for purchases prior to 6/24/02	1.63 (41.4)

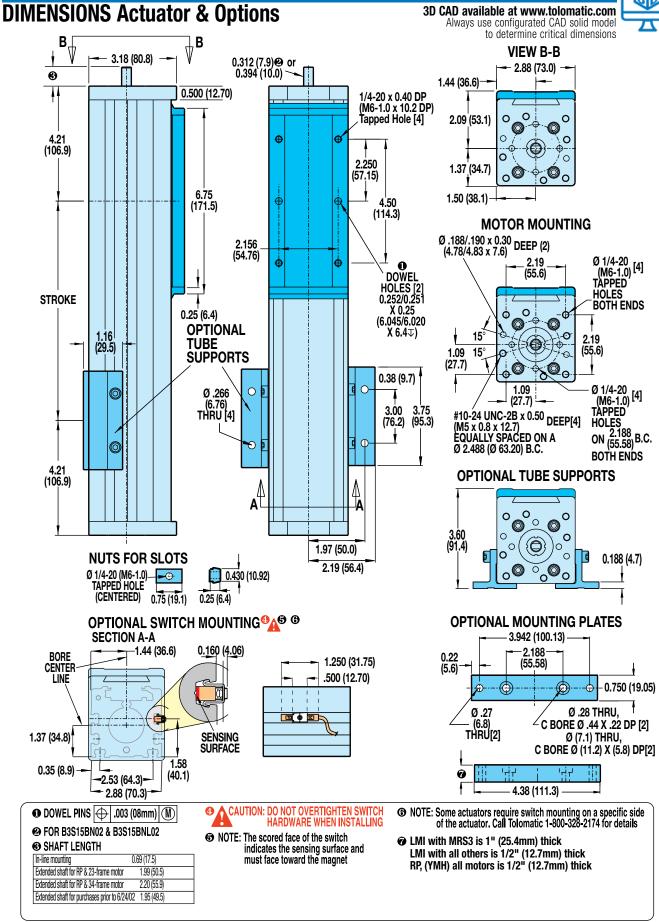
**BORE CENTER LINE** 

CAUTION: DO NOT OVERTIGHTEN SWITCH HARDWARE WHEN INSTALLING

NOTE: The scored face of the switch indicates the sensing surface and must face toward the magnet NOTE: Some actuators require switch mounting on a specific side of the actuator. Call Tolomatic 1-800-328-2174 for details



# B3S15 Electric Screw Drive Rodless Actuators DA belgium

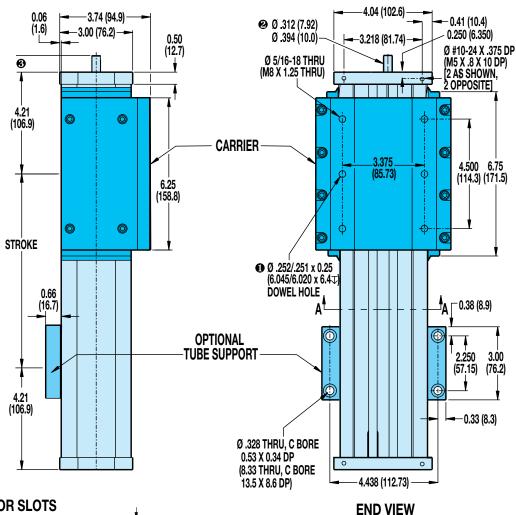


Unless otherwise noted, all dimensions shown are in inches (Dimensions in parenthesis are in millimeters)



### **DIMENSIONS Dual 180° Option**

3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions

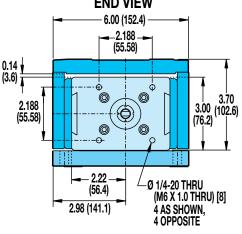


### **NUTS FOR SLOTS**

Ø 1/4-20 (M6 X 1.0) TAPPED HOLE (CENTERED) 0.94 (23.9)



### **SECTION A-A** 0.160 **SENSING** (4.06) SURFACE 1.250 (31.75) 1.58 (40.1) .500 (12.70) (36.6)



0	DOWEL	PINS
---	-------	------

|⊕| .003 (08mm)| M

1.37 (34.8)

◆ FOR B3S15BN02 & B3S15BNL02

### **SHAFT LENGTH**

**BORE CENTER LINE** 

0.69 (17.5) In-line mounting Extended shaft for RP & 23-frame motor 1.99 (50.5) 2.20 (55.9) Extended shaft for RP & 34-frame motor Extended shaft for purchases prior to 6/24/02 1.95 (49.5)

### CAUTION: DO NOT OVERTIGHTEN SWITCH HARDWARE WHEN INSTALLING

 NOTE: The scored face of the switch indicates the sensing surface and must face toward the magnet

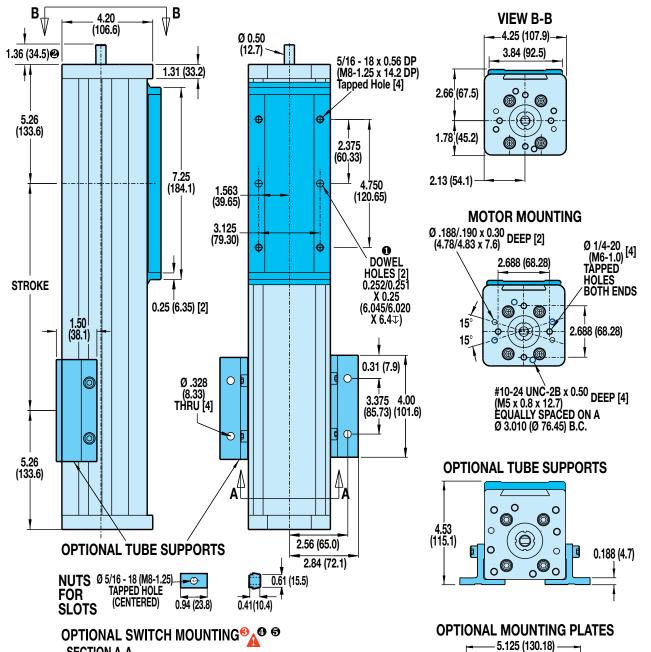
ONOTE: Some actuators require switch mounting on a specific side of the actuator. **Call Tolomatic** 1-800-328-2174 for details



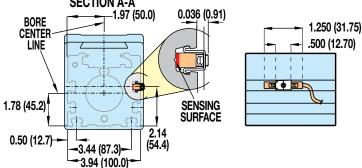
# B3S20 Electric Screw Drive Rodless Actuators DA belgium

### **DIMENSIONS Actuator & Options**

3D CAD available at www.tolomatic.com Always use configurated CAD solid model to determine critical dimensions

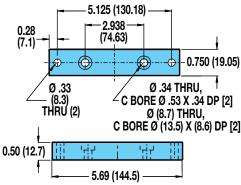


### **SECTION A-A** 1.97 (50.0)



CAUTION: DO NOT OVERTIGHTEN SWITCH **●** DOWEL PINS | **→** | .003 (08mm) | **⑥** | HARDWARE WHEN INSTALLING PFOR EXTENDED SHAFT 2.11 (53.6)

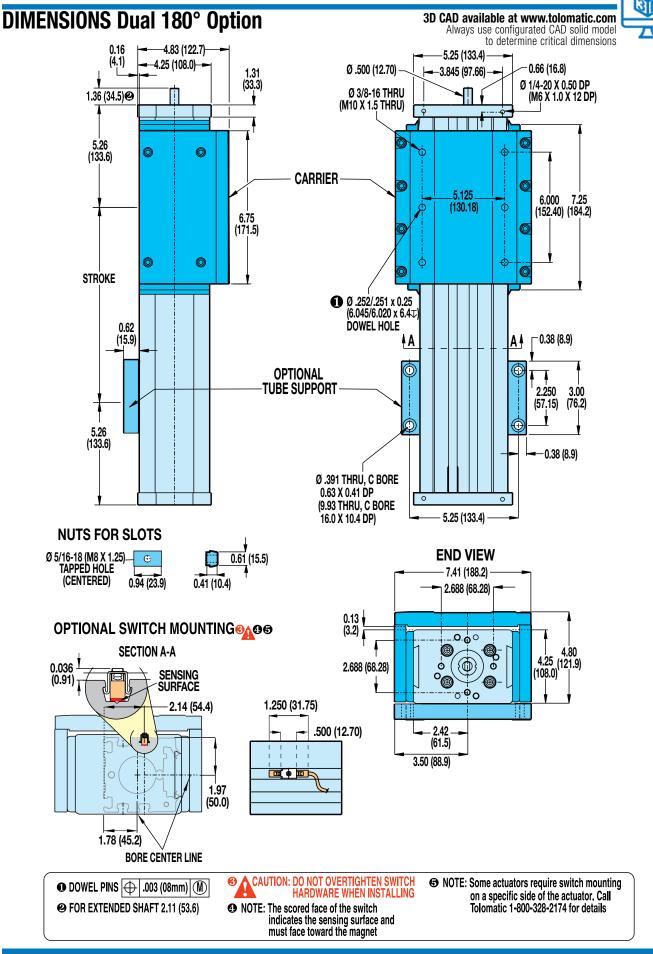
NOTE: The scored face of the switch indicates the sensing surface and must face toward the magnet



NOTE: Some actuators require switch mounting on a specific side of the actuator. Call Tolomatic 1-800-328-2174 for details



# B3S20 Electric Screw Drive Rodless Actuators DA belgium





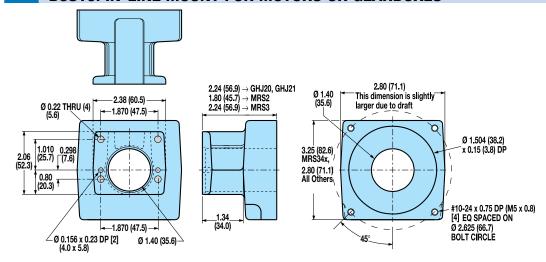
LDA belgium

### **B3S Electric Screw Drive Rodless Actuators**

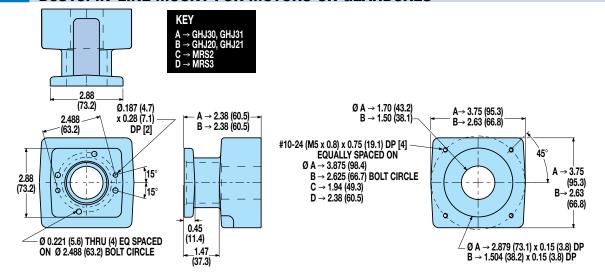
### **DIMENSIONS Actuator & Options**

**3D CAD available at www.tolomatic.com**Always use configurated CAD solid model
to determine critical dimensions

### **B3S10: IN-LINE MOUNT FOR MOTORS OR GEARBOXES**

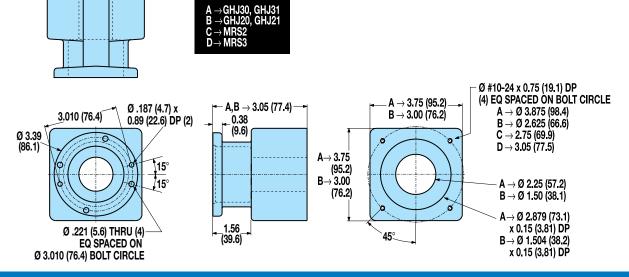


### B3S15: IN-LINE MOUNT FOR MOTORS OR GEARBOXES



### B3S20: IN-LINE MOUNT FOR MOTORS OR GEARBOXES

KEY





### **B3S Electric Screw Drive Rodless Actuators**

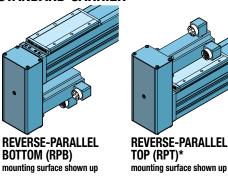
### **DIMENSIONS Reverse Parallel Mounting**

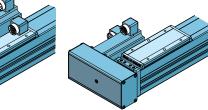
3D CAD available at www.tolomatic.com

LDA belgium

Always use configurated CAD solid model to determine critical dimensions





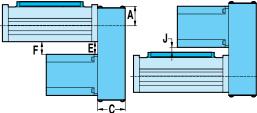


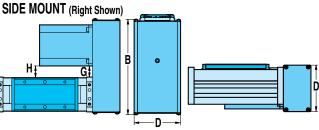
**REVERSE-PARALLEL** 

**REVERSE-PARALLEL** RIGHT (RPR)

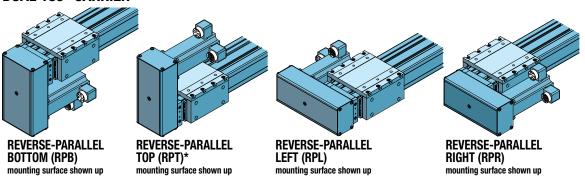
LEFT (RPL) mounting surface shown up mounting surface shown up

**TOP MOUNT BOTTOM MOUNT** 





### **DUAL 180° CARRIER**



### **Reduction Drive Weight**

		kg	lb
10	1:1 & 2:1 Ratio	0.93	2.06
15	1:1 Ratio	0.98	2.17
15	2:1 Ratio	1.09	2.40
	1:1 Ratio	1.39	3.07
20	2:1 Ratio	1.47	3.23
20	1:1 Ratio	1.42	3.13
	2:1 Ratio	1.49	3.29

### **Reduction Inertia at Motor Shaft**

		kg-cm <sup>2</sup>	lb-in <sup>2</sup>
10	1:1 Ratio	0.2559	0.0875
10	2:1 Ratio	0.3291	0.1125
15	1:1 Ratio	0.2043	0.0700
15	2:1 Ratio	0.2767	0.0950
20	1:1 Ratio	0.3447	0.1180
20	2:1 Ratio	0.2928	0.1000

\*A NOTE: RPT is generally not recommended because the load may interfere with the motor. Stops or spacers may be required.

**Reduction Efficiency: 0.95** 

	Frame Size	A	В	C	D	E	F	G	Н	J
10	23	42.6	178.6	54.0	82.6	45.6	46.8	37.6	38.4	26.9
15	23	36.6	191.3	54.0	82.6	44.1	44.1	40.8	42.3	25.3
13	34	53.8	208.6	60.3	101.6	27.7	27.7	24.4	25.9	8.9
20	23	63.8	238.4	60.3	101.6	59.5	59.6	50.8	54.7	37.2
20	34	63.8	251.5	60.3	101.6	43.2	43.2	34.4	38.4	20.9

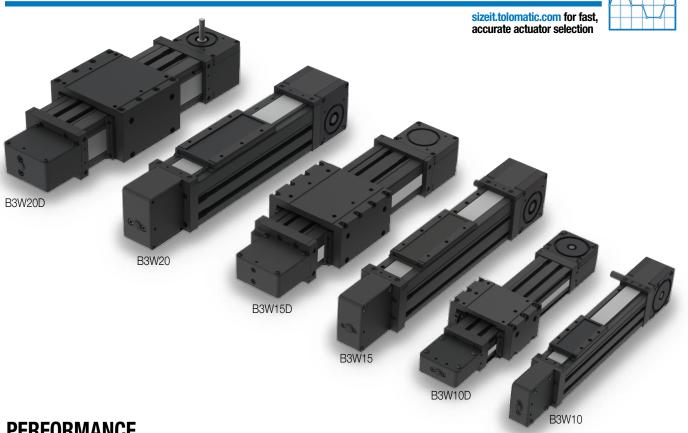
	Frame Size	A	В	C	D	E	F	G	Н	J
10	23	1.68	7.03	2.13	3.25	1.80	1.84	1.48	1.51	1.06
15	23	1.44	7.53	2.13	3.25	1.74	1.74	1.61	1.67	1.00
13	34	2.12	8.21	2.38	4.00	1.09	1.09	0.96	1.02	0.35
20	23	2.51	9.38	2.38	4.00	2.34	2.35	2.00	2.16	1.47
20	34	2.51	9.90	2.38	4.00	1.70	1.70	1.36	1.51	0.82

Dimensions in millimeters

Dimensions in inches





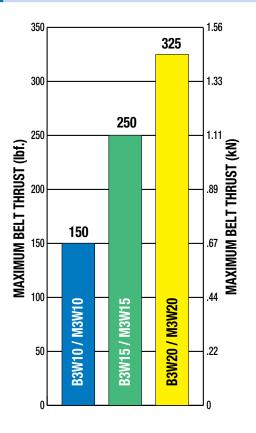


### **PERFORMANCE**

### **CARRIER SPEED CAPABILITIES**

### LINEAR VELOCITY (mm/sec) 5,080 1,270 3,810 4,000 °C 3,500 3,000 2,500 2,000 2,000 1,500 1,000 500 200 LINEAR VELOCITY (in/sec)

### MAXIMUM BELT THRUST

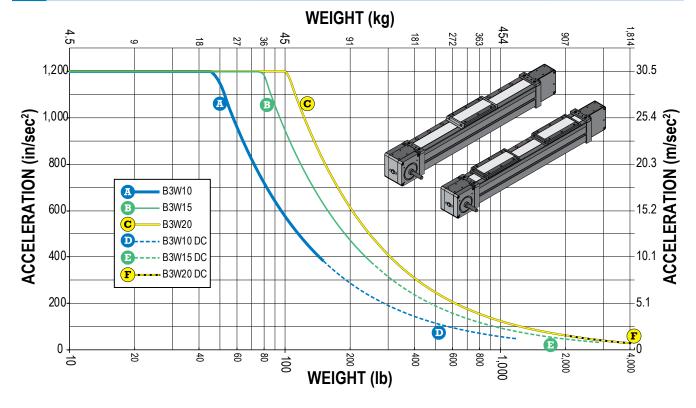


**B3W Electric Belt Drive Rodless Actuators** 

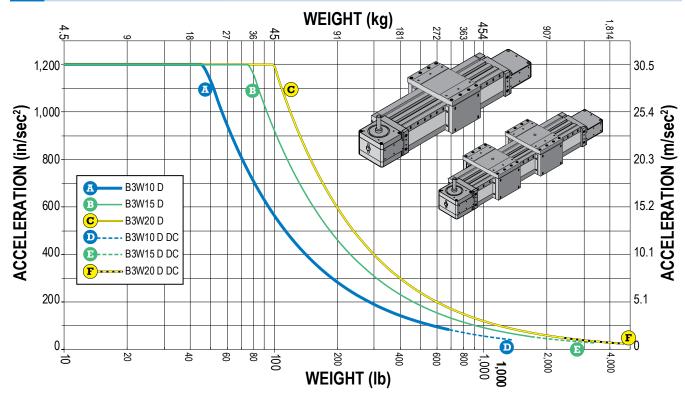
LDA belgium

PRMANCE sizeit.tolomatic.com for fast, accurate actuator selection

### B3W STANDARD CARRIER - MAXIMUM ACCELERATION AS A FUNCTION OF LOAD WEIGHT



### B3W WITH DUAL 180° CARRIER - MAXIMUM ACCELERATION AS A FUNCTION OF LOAD WEIGHT



### **B3W Electric Belt Drive Rodless Actuators**

### **SPECIFICATIONS**

sizeit.tolomatic.com for fast, accurate actuator selection

### **METRIC**

### **INCH (U.S. Conventional)**

							- \		,
			B3W10	B3W15	B3W20		B3W10	B3W15	B3W20
	Max. Stroke	mm	14,579	10,566	8,128	in	574	416	320
	Max. Velocity	m/sec	5.08	5.08	5.08	in/sec	200	200	200
	Max. Acceleration	m/sec <sup>2</sup>	30.48	30.48	30.48	in/sec²	1,200	1,200	1,200
	Max. Input Torque	N-m	8.5	21.2	32.2	lb-in	75.2	188.0	285.0
.1 60	Standard (single) Carrier	N-m	1.06	1.41	3.18	lb-in	9.38	12.5	28.13
Break- away Torque	Dual 180° or Aux. Carrier	N-m	1.34	1.69	3.53	lb-in	11.88	15	31.25
@ ** <u>F</u>	Dual 180 & Aux Carrier	N-m	1.91	2.82	5.37	lb-in	16.88	25	47.5
	Pulley Pitch Dia.	mm	25.48	38.2	44.55	in	1.003	1.504	1.754
	Stroke per Rev.	mm/rev	80.04	120.02	139.95	in/rev	3.151	4.725	5.51
	Repeatability	mm	+/- 0.05	+/- 0.05	+/- 0.05	in	+/- 0.002	+/- 0.002	+/- 0.002
	Straightness & Flatness <sup>1</sup>	mm	0.017 x L*	0.017 x L*	0.017 x L*	in	0.00067 x L*	0.00067 x L*	0.00067 x L*
	Temp. Range <sup>2</sup>	°C	4 - 54	4 - 54	4 - 54	°F	40 - 130	40 - 130	40 - 130
	IP Rating <sup>3</sup>	IP	44	44	44	IP	44	44	44
	Inertia (zero stroke)	kg-cm <sup>2</sup>	0.833	4.073	7.786	lb-in²	0.2846	1.3917	2.6607
	Inertia (per unit of stroke)	kg-cm <sup>2</sup> /mm	0.00018	0.0002	0.00131	lb-in²/in	0.0016	0.0017	0.0114
	Inertia of pulley	kg-cm <sup>2</sup>	0.027	0.219	0.422	lb-in²	0.0093	0.0748	0.1441
	Inertia of carrier	kg-cm <sup>2</sup>	0.305	1.489	2.847	lb-in²	0.1041	0.5089	0.9728
	Weight of pulley	kg	0.0068	0.0244	0.047	lb	0.015	0.054	0.1036
					1	ı			1

Weight of pulley	kg	0.0068	0.0244	0.047	lb	0.015	0.054	0.1036
Weight of carrier	kg	0.39	0.71	0.97	lb	0.85	1.56	2.14
Weight (zero stroke)	kg	3.42	11.39	16.06	lb	7.54	25.12	35.4
Weight (per unit of stroke)	kg/mm	0.0069	0.0071	0.0128	lb/in	0.389	0.395	0.716

		B3W10D	B3W15D	B3W20D		B3W10D	B3W15D	B3W20D
Weight of carrier	kg	1.09	3.02	4.86	lb	2.40	6.66	10.72
Weight (zero stroke)	kg	4.36	13.71	19.94	lb	9.62	30.22	43.97
Weight (per unit of stroke)	g/mm	8.93	13.57	22.14	lb/in	0.50	0.76	1.24



- <sup>1</sup>The listed values relating to straightness/flatness are intended for reference purposes only, and not as an engineering standard of absolute tolerance for a given actuator. Appropriate installation is the single most important factor in reducing such deviation, so good engineering practices such as measurement, mapping, etc. must be employed in applications with stringent straightness/flatness requirements.
- <sup>2</sup> Heat generated by the motor and drive should be taken into consideration as well as linear velocity and work cycle time. For applications that require operation outside of the recommended temperature range, contact the factory.

LARGE FRAME MOTORS AND SMALLER SIZE ACTUATORS: Cantilevered motors need to be supported if subjected to continuous rapid reversing duty and/or under dynamic conditions.

NOTE: Zero stroke inertia and weight are for an assembled actuator (including carrier, pulley and belt material) that has zero stroke length. To calculate system inertia use the formula below:

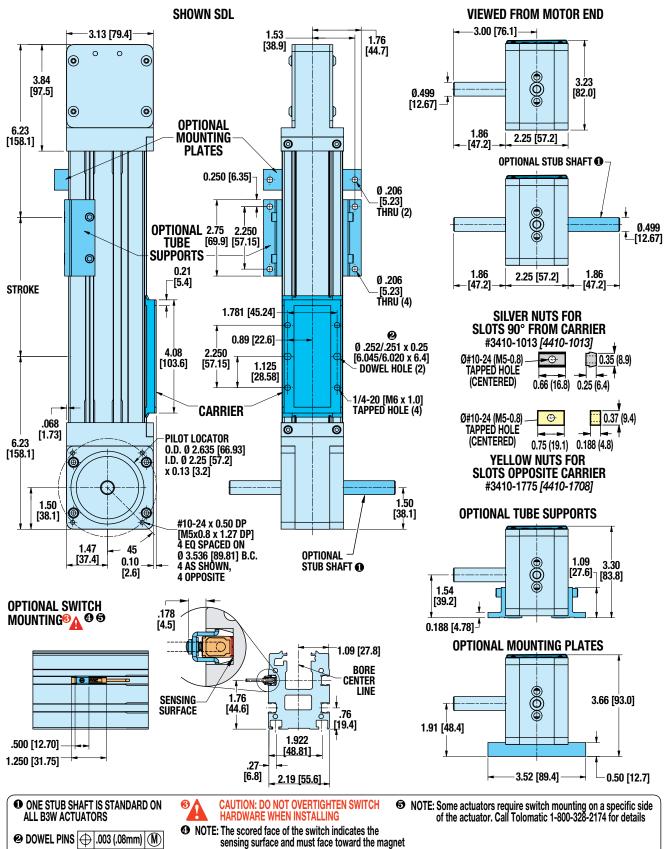
 $\textbf{System Inertia} = \textbf{Inertia}_{\text{(zero stroke)}} + \left[ \textbf{Inertia}_{\text{(per unit of stroke)}} \ \textbf{x number of units} \right]$  (For weight calculation substitute inertia with weight in the above formula)



³ Protected against ingress of solid particles greater than 1 mm (.039 in) and splashing water.
\*"L" is maximum distance between supports - See Support Recommendations graph pg B3\_9.

# B3W10 Electric Belt Drive Rodless Actuators LDA belgium

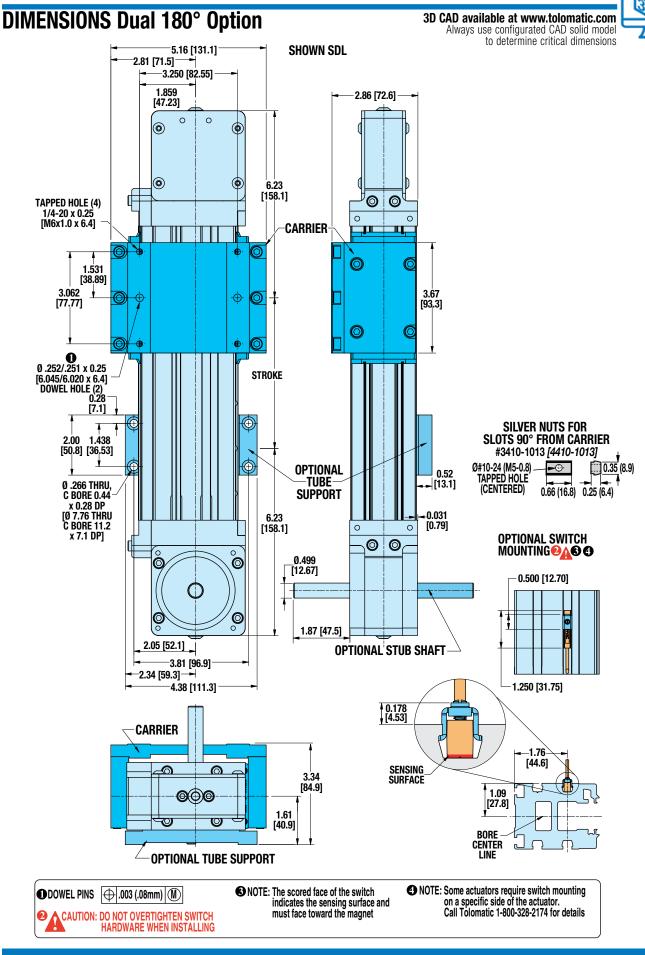




Unless otherwise noted, all dimensions shown are in inches [Dimensions in brackets are in millimeters]



# B3W10 Electric Belt Drive Rodless Actuators LDA belgium





1.75

[44.5]

[43.7]

0.11

[2.7]

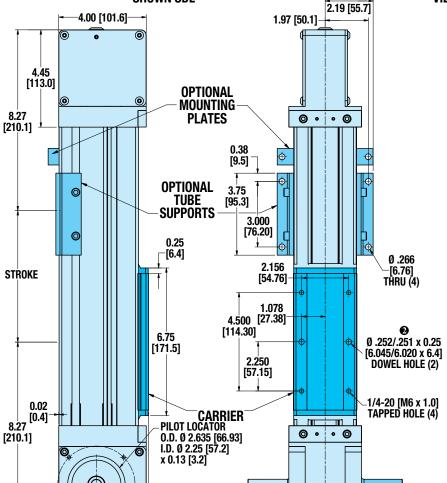
# B3W15 Electric Belt Drive Rodless Actuators LDA belgium

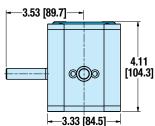
### **DIMENSIONS Actuator & Options**

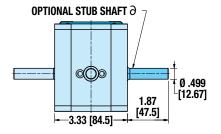
**SHOWN SDL** 

3D CAD available at www.tolomatic.com Always use configurated CAD solid model

### to determine critical dimensions **VIEWED FROM MOTOR END**

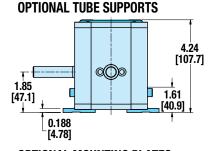


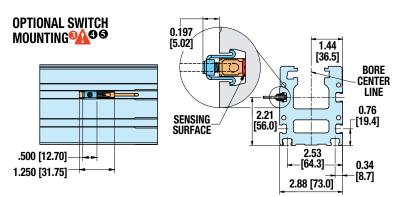




### **NUTS FOR SLOTS** 1/4-20 (M6-1.0) TAPPED HOLE 0.43 [10.9] 0.75 (CENTERED)

# [19.1] [6.4]





#10-24 x 0.50

4 OPPOSITE

[M5 x 0.8 x 12.7]

4 EQ SPACED ON Ø 3.536 [89.81] B.C. 4 AS SHOWN

### **OPTIONAL MOUNTING PLATES** 4.59 [116.6] 2.21 [56.1] 4.38 [111.3] 0.50 [12.7]

• ONE STUB SHAFT IS STANDARD ON **ALL B3W ACTUATORS** 

**❷** DOWEL PINS |⊕|.003 (.08mm)| **M**)

CAUTION: DO NOT OVERTIGHTEN SWITCH HARDWARE WHEN INSTALLING

3.53 [89.7]

**OPTIONAL** 

STUB SHAFT **①** 

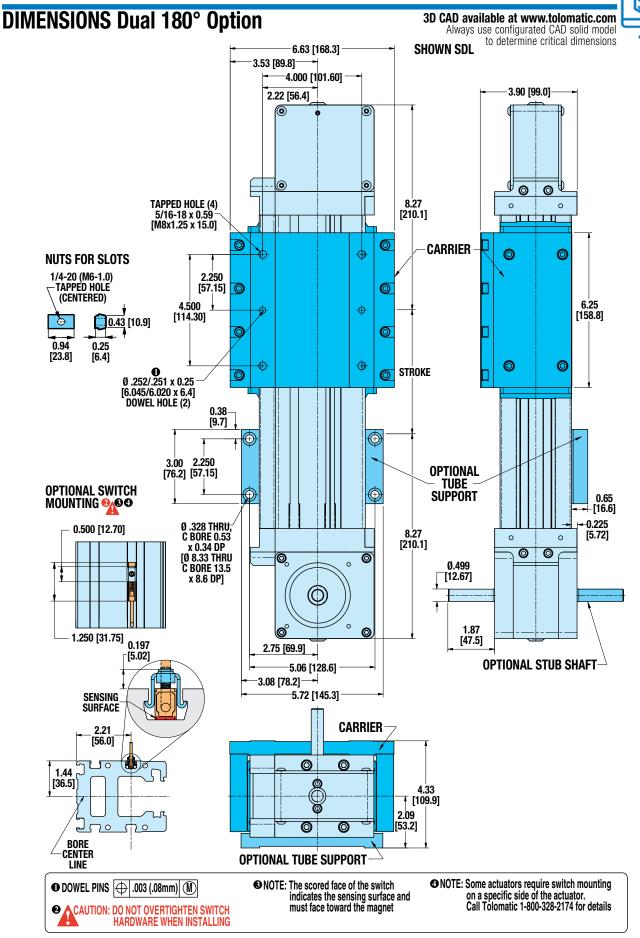
- NOTE: Some actuators require switch mounting on a specific side of the actuator. Call Tolomatic 1-800-328-2174 for details
- NOTE: The scored face of the switch indicates the sensing surface and must face toward the magnet

Unless otherwise noted, all dimensions shown are in inches [Dimensions in brackets are in millimeters]



[44.5]

# B3W15 Electric Belt Drive Rodless Actuators LDA belgium

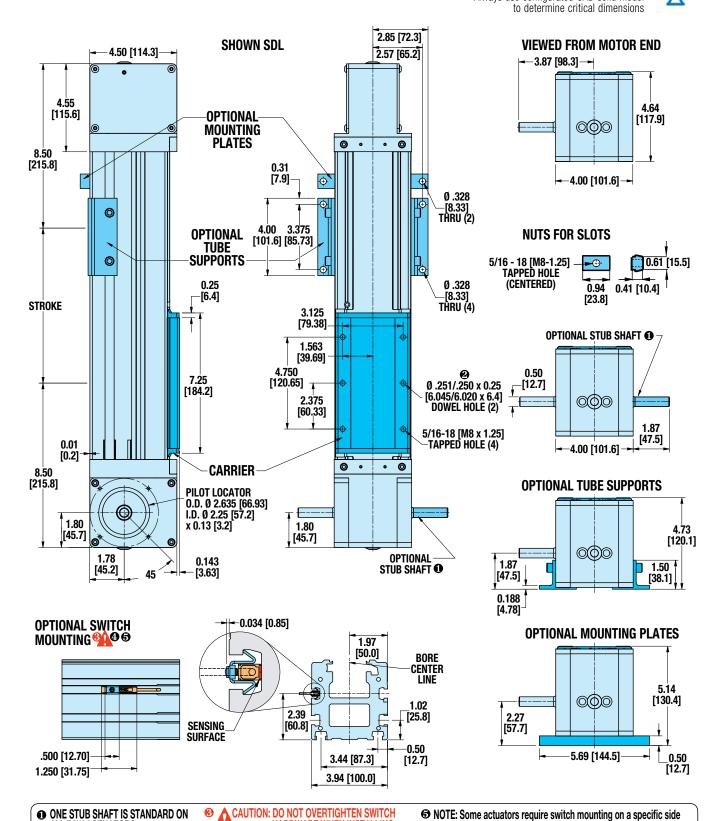




# B3W20 Electric Belt Drive Rodless Actuators LDA belgium

3D CAD available at www.tolomatic.com
Always use configurated CAD solid model

### **DIMENSIONS Actuator & Options**



Unless otherwise noted, all dimensions shown are in inches [Dimensions in brackets are in millimeters]



**ALL B3W ACTUATORS** 

② DOWEL PINS ⊕ | .003 (.08mm) (Ŋ)

of the actuator. Call Tolomatic 1-800-328-2174 for details

HARDWARE WHEN INSTALLING

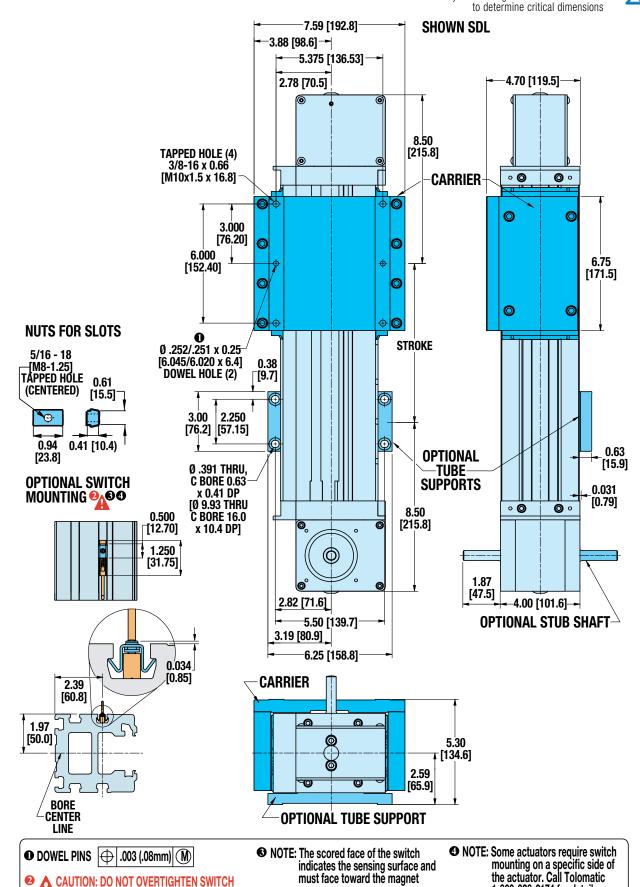
sensing surface and must face toward the magnet

NOTE: The scored face of the switch indicates the

# B3W20 Electric Belt Drive Rodless Actuators LDA belgium

### **DIMENSIONS Dual 180° Option**

3D CAD available at www.tolomatic.com
Always use configurated CAD solid model





HARDWARE WHEN INSTALLING

1-800-328-2174 for details

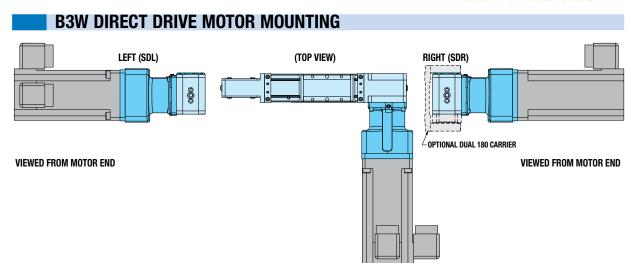
### **B3W Electric Belt Drive Rodless Actuators**

### **MOTOR MOUNTING**

3D CAD available at www.tolomatic.com

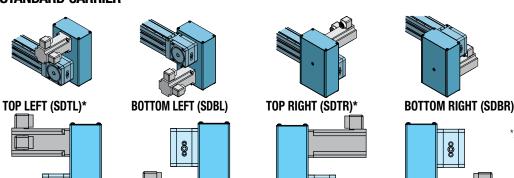
LDA belgium

Always use configurated CAD solid model to determine critical dimensions



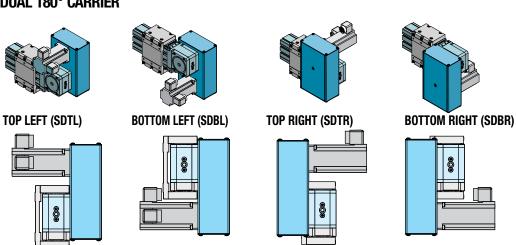
### **B3W(D) REDUCTION DRIVE MOTOR MOUNTING**

### STANDARD CARRIER



8

### **DUAL 180° CARRIER**





\*▲ NOTE: SDTL &

motor. Stops or spacers may be required.

SDTR are generally not recommended because the load may interfere with the

### **B3S & B3W Electric Rodless Actuators**

### LDA belgium

### **SWITCHES**



There are 10 sensing choices: DC reed, form A (open) or form C (open or closed); AC reed (Triac, open); Hall-effect, sourcing, PNP (open); Hall-effect, sinking, NPN (open); each with either flying leads or QD (quick disconnect). Commonly used to send analog signals to PLC (programmable logic controllers), TLL, CMOS circuit or other controller device. These switches are activated by the actuator's magnet.

Switches contain reverse polarity protection. QD cables are shielded; shield should be terminated at flying lead end.

If necessary to remove factory installed switches, be sure to reinstall on the same of side of actuator with scored face of switch toward internal magnet.

### **SPECIFICATIONS**

SELUII IUATIUNS										
		REE	D DC		REE	D AC	HALL-EFFECT DC			
ORDER CODE	RT	RM	BT	BM	CI	CM	TT	TM	KT	KM
LEAD	5m	QD*	5m	QD*	5m	QD*	5m	QD*	5m	QD*
CABLE SHIELDING	Unshielded	Shielded†	Unshielded	Shielded†	Unshielded	Shielded†	Unshielded	Shielded†	Unshielded	Shielded†
SWITCHING LOGIC	"A" Norm	ally Open	"C" Norma <b>ll</b> y (	Open or Closed	Triac Norn	na <b>ll</b> y Open	PNP (Sourcii Op		NPN (Sinking)	Norma <b>ll</b> y Open
MECHANICAL CONTACTS	Single-Pole S	Single-Throw	Single-Pole [	ingle-Pole Double-Throw Single-		Single-Throw	NO,	These Are Soli	d State Compon	ents
COIL DIRECT	Ye	es	Y	es	Ye	es	<del>-</del>			
POWER LED	None		]	one	No	ne	None		None	
SIGNAL LED	Red 🖭	TOL-O-MATIC	IVC		Red • [TOIL-O-MAGNE]		Red 🖭	Red • Trol-o-MATIC		
OPERATING VOLTAGE	200 Va	lc max.	120 Vo	dc max.	120 Va	ic max.	5 - 25 Vdc			
OUTPUT RATING			_	,	_	_			25 Vdc, 200mA dc	
OPERATING TIME	0.6 ms (including			ec max. g bounce)	_	_	< 10 micro sec.			
OPERATING TEMPERATURE			-40°F [-40°C]	to 158°F [70°C]			0°F [-18°C] to 150°F [66°C]			
RELEASE TIME		1.0 mse	ec. max.		-	<del>-</del>			_	
ON TRIP POINT			_	,	_	_	150 Gauss maximum			
OFF TRIP POINT			_		_	_		40 Gauss	40 Gauss minimum	
**POWER RATING (WATTS)		.0 §		) § §	10	0.0		5	.0	
VOLTAGE DROP	2.6 V typica			IA .	-	_		-		
RESISTANCE		0.1 <b>Ω</b> Ini	itial (Max.)		-	_	_			
CURRENT CONSUMPTION —			1 Amp at 86°F [30°C]	0.5 Amp at 140°F [60°C]	200 mA at 25 Vdc					
FREQUENCY		_	_		47 -	63 Hz		<u>-</u>	_	
CABLE MIN. STATIC					0.630"	[16mm]				
BEND RADIUS DYNAMIC					Not Reco	mmended				



### A CAUTION: DO NOT OVER TIGHTEN SWITCH HARDWARE WHEN INSTALLING!



\*\* **WARNING**: Do not exceed power rating (Watt = Voltage X Amperage). Permanent damage to sensor will occur.

\*QD = Quick Disconnect; Male coupler is located 6" [152mm] from sensor,

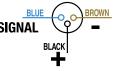
Female coupler to flying lead distance is 197" [5m] also see Cable Shielding specification above







Quick disconnect SIGNAL



Reed Switch Life Expectancy: Up to 200,000,000 cycles (depending on load current, duty cycle and environmental conditions)

†Shielded from the female quick disconnect coupler to the flying leads. Shield should be terminated at flying lead end.

<sup>§</sup> Maximum current 500mA (not to exceed 10VA) Refer to Temperature vs. Current graph and Voltage Derating graph

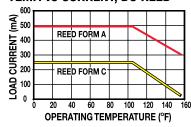


### **B3S & B3W Electric Rodless Actuators**

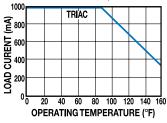
### **SWITCH PERFORMANCE**

### **PERFORMANCE**

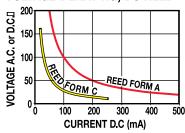
TEMP. vs CURRENT, DC REED



**TEMP. vs CURRENT, AC REED** 

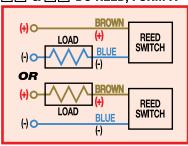


**VOLTAGE DERATING, DC REED** 

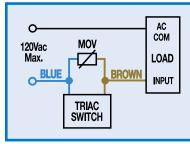


### **WIRING DIAGRAMS**

RT & RM DC REED, FORM A







### **INSTALLATION INFORMATION**

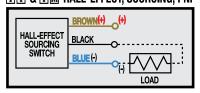


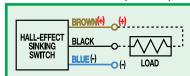
THE NOTCHED
FACE OF THE
SWITCH INDICATES
THE SENSING
SURFACE AND
MUST FACE
TOWARD THE
MAGNET.











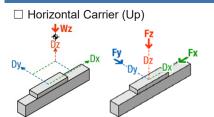


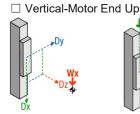
THE NOTCHED GROOVE IN THE ACTUATOR INDICATES THE GROOVE TO INSTALL THE SWITCH. CONTACT TOLOMATIC IF SWITCHES ARE REQUIRED ON ANOTHER SIDE OF ACTUATOR.

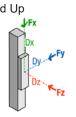
# Electric Rodless Actuator Application Worksheet gium

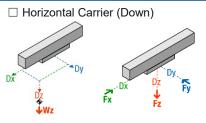
USE THE TOLOMATIC SIZING AND SELECTION SOFTWARE AVAILABLE ON-LINE AT www.tolomatic.com or call Tolomatic at 1-800-328-2174. We will provide any assistance needed to determine the proper actuator for the job.

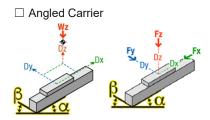
### **ACTUATOR ORIENTATION**

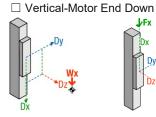


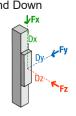


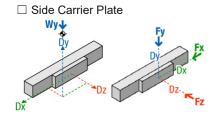












α angle: degrees β angle: \_

### **ACTUATOR REQUIREMENTS**

Stroke length:	_ □ inches □ millimeters
No. of Cycles:	$\square$ per minute $\square$ per hour
Actuator to Hold Position:	$\square$ required $\square$ not required
If Hold Required: □	after move $\square$ during power loss
<b>Motor:</b> □ Third Party Motor	☐ Tolomatic Motor

APPLICATION ENVIRONMEN	
APPI II. AIII IN ENVIRUNIVIEN	4 1

Ambient Temperature: □ °F □ °C
Actuator Environment Description and Ingress Protection Requirements:

### **MOTION & FORCES**

Extend		Retract
Move Distance:	_ □ in □ mm	Move Dista
Move Time:	_ seconds	Move Time
Max. Speed:	_ □ in/s □ mm/s	Max. Speed
Dwell Time After Move:	_ seconds	Dwell Time
Load		Force
Load:	_	Force:
Supported by Actuator:	_ %	Force Dire
Center of Load:		Direction of
D <sub>X</sub> :	$\Box$ in $\Box$ mm	Center of A
D <sub>Y</sub> :	_ □ in □ mm	D <sub>x</sub> :
D <sub>z</sub> :	_ □ in □ mm	D <sub>Y</sub> :
Assign to Moves:	$\square$ Extend $\square$ Retract	D <sub>z</sub> :

Move Distance:	🗆 in 🗆 mm		
Move Time:	seconds		
Max. Speed:	🗆 in/s 🗆 mm/s		
Dwell Time After Move:	seconds		
Force			
Force:			
Force Direction:	$\square$ Toward $\square$ Away		
Direction of Applied Force:	$\square \; F_x \; \square \; F_y \; \square \; F_z$		
Center of Applied Force:			
D <sub>X</sub> :			
D <sub>Y</sub> :			
D <sub>z</sub> :			
Assign to Moves:	□ Extend □ Retract		





### **SELECTION GUIDELINES**

The process of selecting a load bearing actuator for a given application can be complex. It is highly recommended that you contact Tolomatic or a Tolomatic Distributor for assistance in selecting the best actuator for your application. The following overview of the selection guidelines are for educational purposes only.

tuator performance and application safety. If either load or any of your moments exceed figures indicated in the Moment and Load Capacity table (page B3\_8) for the actuator consider:

- 1) Higher capacity bearing style
- 2) A larger actuator size
- 3) Auxiliary carrier
- 4) External guide system

# CHOOSE ACTUATOR 3

Choose an actuator that has the (A) thrust, (B) speed and (C) moment load capacity to move the load. **A.** Max Thrust: B3S see page B3\_11;

B3W see page B3\_25 **B.** Max. Speed: B3S see critical speed graphs page B3\_13 to B3\_15; All B3W

sizes = 200 in/sec (5m/sec).

C. Moment & Load B3S &
B3W see page B3\_8

# 2 COMPARE LOAD TO MAXIMUM LOAD CAPACITIES

Calculate the application load (combination of load mass and forces applied to the carrier) and application bending moments (sum of all moments Mx, My, and Mz applied to the carrier). Be sure to evaluate the magnitude of dynamic inertia moments. When a rigidly attached load mass is accelerated or decelerated. its inertia induces bending moments on the carrier. Careful attention to how the load is decelerated at the end of the stroke is required for extended ac-

# 3 CALCULATE LOAD

For loads with a center of gravity offset from the carrier account for both applied (static) and dynamic loads. The load factor (LF) must not exceed the value of 1.5.

$$L_F = \frac{Mx}{Mx_{max}} + \frac{My}{My_{max}} + \frac{Mz}{Mz_{max}} + \frac{Fy}{Fy_{max}} + \frac{Fz}{Fz_{max}} \le 1.5$$

If LF does exceed the value of 1.5, consider the four choices listed in step #2.

# 4 ESTABLISH YOUR MOTION PROFILE AND CALCULATE ACCELERATION RATE

Using the application stroke length and maximum carrier velocity (or time to complete the linear motion), establish the motion profile. Select either triangular (accel-decel) or trapezoidal (accel-constant speeddecel) profile. Now calculate the maximum acceleration and deceleration rates of the move. For the B3S Acceleration/deceleration should not exceed critical speed (page B3\_13) chosen. For the B3W acceleration/deceleration should not exceed 1200 in/sec<sup>2</sup> (30.48 m/ sec<sup>2</sup>). Also, do not exceed safe rates of dynamic inertia moments determined in step #3.

# 5 SELECT THE LEAD SCREW (B3S ONLY)

Based on the application requirements for accuracy, backlash, quiet operation, life, etc. select the appropriate lead screw type (Acme screw with a solid nut or ball screw with a standard or antibacklash nut) and the pitch (lead). For additional information on screw selection, consult "Which Screw? Picking the Right Technology" (#9900-4644) available at www.tolomatic.com.

# 6 SELECT MOTOR (GEARHEAD IF NECESSARY) AND DRIVE

To help select a motor and drive, use the sizing equations located in the Engineering Resources section [ENGR\_] of the Tolomatic Electric Products Catalog (#3600-4609) to calculate the application thrust and torque requirements. Refer to Motor sections to determine the motor and drive.

# DETERMINE TUBE SUPPPORT/ MOUNTING PLATE/ T-NUT REQUIREMENTS

- Consult the Tube Support Requirements graph for the model selected (page B3 9)
- Cross reference the application load and maximum distance between supports
- for the screw/nut combination chosen. **For the B3W** acceleration/deceleration should not exceed 1200 in/sec² (30.48 m/sec²). Also, do not exceed safe

### LDA belgium

# **8**CONSIDER OPTIONS

- Choose metric or inch (US Conventional) load mounting. (When ordering use
   SIX for inch or SIM for metric)
- Switches Reed, Solid State PNP or NPN, all available normally open or normally closed.

# ORIENTATION (B3W ONLY)

Belt drives used in vertical applications will not prevent a load falling in the event of a timing belt failure. A secondary safety measure is recommended if a B3W is used in a safety critical vertical application.

Use the Tolomatic Sizing & Selection Software or call Tolomatic at 1-800-328-2174







### **B3S Electric Screw Drive Rodless Actuators**



**Built-to-Order** 

### **ORDERING**

BASE MODEL OPTIONS

### B3S 20 D BNL02 SK36 LMI DC18 TS2 BM2 TN8

### **MODEL TYPE**

**B3S** B3S Screw Drive Rodless Actuator

SIZE

10,

15, 20

### **DUAL 180° CARRIER**

Dual 180° Carrier

### **NUT/SCREW CONFIGURATION**

INCH MODELS (US Conventional)	METRIC Models†				
SOLID NUT / PITCH (turn/in)	SOLID NUT / LEAD (mm/turn)				
♦\$N01 ♦\$N02, \$NA02 \$N05	♦SN12				
♦SN (Solid Nut) not available for 20 Size					
BALL NUT / PITCH (turn/in)	BALL NUT / LEAD (turn/in)				
BN02, BNL02	BNM10				
BN05, BNL05	BN05, BNL05				
BN08, BNL08	BN08, BNL08				

† The metric version provides metric tapped holes for mounting of the load to the carrier and of the actuator to mounting surfaces

### STROKE LENGTH & MOUNTING TYPE

**SK**\_\_\_\_\_ Stroke, enter desired stroke length in inches

**SM†**\_\_\_.\_ Stroke, enter desired stroke length in millimeters

**NOTE:** Actuator mounting threads and mounting fasteners will be either inch or metric; depending on how stroke length is indicated

**SK**=inch mounting

**SM**= metric mounting

### **MOTOR MOUNTING / REDUCTIONS**

### (must choose one)

**LMI** In-Line mounting

LME23 Ext. shaft for RP & 23 frame motor

**LME34** Ext. shaft for RP & 34 frame motor

\*LMX Extended shaft - old style (see note) \*For replacement actuators with extended motor

shafts purchased prior to 6/24/02, use the LMX configuration code.

### A motor size and code must be A selected when specifying a reverseparallel mounting configuration.

**RPL1** 1:1 Reverse-Parallel mount left

**RPR1** 1:1 Reverse-Parallel mount right

**RPB1** 1:1 Reverse-Parallel mount bottom

**RPT1** 1:1 Reverse-Parallel mount top

**RPL2** 2:1 Reverse-Parallel mount left

**RPR2** 2:1 Reverse-Parallel mount right **RPB2** 2:1 Reverse-Parallel mount bottom

**RPT2** 2:1 Reverse-Parallel mount top

### **AUXILIARY CARRIER**

**DC** Auxiliary Carrier, then center-to-center spacing desired in inches (SK) or millimeters (SM).

(Same unit of measure as stroke length is required) Center-to-center spacing between carriers adds to overall length of the actuator, this distance will not be subtracted from stroke length specified in the previous step.

### SUPPORTS AND MOUNTING PLATES

### (both may be selected)

**TS** \_ Tube Supports plus quantity desired \*\*MP\_Mounting Plates plus quantity desired

\*\*Mounting plates are not available on B3SD Dual 180° models.

### **SWITCHES**

(Quantity desired follows product code)

**RM** Reed Switch (Form A) with 5-meter lead/QD (Quick-disconnect)

Reed Switch (Form A) with 5-m lead

**BM**\_ Reed Switch (Form C) with 5-meter lead/QD

Reed Switch (Form C) with 5-m lead

KM Hall-effect Sinking Switch with 5-meter lead/QD

Hall-effect Sinking Switch w/ 5-m lead

TM\_ Hall-effect Sourcing Switch with 5-meter lead/QD

TT\_ Hall-effect Sourcing Switch with 5-meter lead

CM TRIAC Switch with 5-meter lead/QD

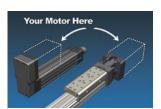
CT TRIAC Switch with 5-meter lead

### **T-NUTS**

**TN** Additional T-Nuts and quantity

### **FOOD GRADE LUBRICATION**

LUB Grease, Food/Drug



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Visit www.tolomatic.com/ymh to find your motor/actuator match!

Not all codes listed are compatible with all options.

Use Tolomatic Sizing Software to determine available options and accessories based on your application requirements.

NOTE: Brakes mounted on reduction drives (especially in vertically positioned actuators) will not prevent back driving of the screw and the load falling under gravity in the event of a timing belt failure. An inline motor mount with a fail-safe brake mounted directly to the actuator shaft or a special geared or thru-shaft reduction drive construction should be considered if a brake is required in a safety critical application. Contact Tolomatic for alternative reduction drive brake mounting options.

Gearheads may be used with reduction drives. However, the torque on the belt and internal reduction drive components must remain below the capabilities of the assembly to prevent belt slipping or premature failure. Contact Tolomatic for additional information if required.

FIELD RETROFIT KITS							
ITEM	B3S10_SM	B3S15_SM	B3S20_SM	B3S10_SK	B3S15_SK	B3S20_SK	
Tube Supports	4410-9006	4415-9006	4420-9006	3410-9006	3415-9006	3420-9006	
Tube Supports (B3SD Dual 180° models)	4410-9026	4415-9026	4420-9026	3410-9026	3415-9026	3420-9026	
1/2" Mounting Plates	4410-9030	4415-9030	4420-9030	3410-9142	3415-9056	3420-9056	
1" Mounting Plates	4410-9031	4415-9031	1	3410-9057	3415-9057	_	



### **B3W Electric Belt Drive Rodless Actuators**

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Fast delivery Built-to-Order

### **ORDERING**

BASE MODEL
B3W 20D BWS40 SK56 SDTR DC1

DC18 TS2 BM2 TN16

### **MODEL TYPE**

B3W B3W Series Belt Drive

### SIZE

20

10, 15,

### **DUAL 180° CARRIER**

Dual 180° Carrier

### **BELT MATERIAL AND WIDTH**

**BWS18** 18mm Polyurethane Steel belt (B3W10)

**BWS30** 30mm Polyurethane Steel belt (B3W15)

**BWS40** 40mm Polyurethane Steel belt (B3W20)

### STROKE LENGTH & MOUNTING TYPE

SK\_\_\_\_ .\_\_ Stroke, enter desired stroke length in **inches** 

**SM†**\_\_\_\_\_ Stroke, enter desired stroke length in **millimeters** 

**NOTE:** Actuator mounting threads and mounting fasteners will be either inch or metric; depending on how stroke length is indicated

**SK**=inch mounting

**SM**= metric mounting

† The metric version provides metric tapped holes for mounting of the load to the carrier and of the actuator to mounting surfaces

Not all codes listed are compatible with all options.

Use Tolomatic Sizing Software to determine available options and accessories based on your application requirements.

### **MOTOR MOUNTING / REDUCTIONS**

### (must choose one)

SDL, SDLB\* Direct Drive on left SDR, SDRB\* Direct Drive on right

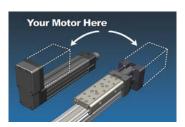
A motor size and code must be selected when specifying a 3:1 reduction.

SDTL, SDTLB\* 3:1 Reduction on top left SDTR, SDTRB\* 3:1 Reduction on top right SDBL, SDBLB\* 3:1 Reduction on bottom left SDBR, SDBRB\*3:1 Reduction on bottom right \*For Dual Stub Shaft option

### **AUXILIARY CARRIER**

**DC\_** \_Auxiliary Carrier, then center-to-center spacing desired in inches (**SK**) or millimeters (**SM**).

(Same unit of measure as stroke length is required)
Center-to-center spacing between
carriers adds to overall length of the
actuator, this distance will not be
subtracted from stroke length specified
in the previous step.



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 Select a high-performance Tolomatic electric actuator and we'll provide a motor-specific interface for your motor. With our online database, you can select from over 60 motor manufacturers and hundreds of models.

Visit **www.tolomatic.com/ymh** to find your motor/actuator match!

### **SUPPORTS AND MOUNTING PLATES**

### (both may be selected)

TS \_ Tube Supports, enter quantity desired

MP\_ Mounting Plates, enter quantity
desired

SWITCHES						
CODE		ТҮРЕ	QUICK- Disconnect	LEAD LENGTH	QUANTITY	
RM		Form A	QD			
RT	REED	TOITITA	no		pe pe	
BM	R	Form C	QD		desir	
BT		T OITH O	no		ıtity	
KM	CT	Sinking	QD	eters	quar	
KT	HALL-EFFECT	Silikiliy	no	5 meters	enter	
TM	1	Sourcing	QD		ode (	
TT	Ŧ	Sourchig	no		After code enter quantity desired	
CM	_	TRIAC	QD			
CT		ITIIAU	no			

### T-NUTS

**TN** \_ Additional T-Nuts, enter quantity

NOTE: Brakes mounted on reduction drives (especially in vertically positioned actuators) will not prevent back driving of the screw and the load falling under gravity in the event of a timing belt failure. An inline motor mount with a fail-safe brake mounted directly to the actuator shaft or a special geared or thru-shaft reduction drive construction should be considered if a brake is required in a safety critical application. Contact Tolomatic for alternative reduction drive brake mounting options.

Gearheads may be used with reduction drives. However, the torque on the belt and internal reduction drive components must remain below the capabilities of the assembly to prevent belt slipping or premature failure. Contact Tolomatic for additional information if required.

FIELD RETROFIT KITS							
ITEM	B3W10_SM	B3W15_SM	B3W20_SM	B3W10_SK	B3W15_SK	B3W20_SK	
Tube Supports	4410-9006	4415-9006	4420-9006	3410-9006	3415-9006	3420-9006	
Tube Supports (B3WD Dual 180° models)	4410-9170	4415-9170	4420-9170	3410-9170	3415-9170	3420-9170	
1/2" Mounting Plates (MRV 23-frame motors)	4410-9030	4415-9030	ı	3410-9056	3415-9056	_	
1/2" Mounting Plates (MRV all frame motors)	_	_	4420-9030	ı	-	3420-9056	
1" Mounting Plates (MRV all frame motors)	4410-9031	_	-	3410-9057	_	_	
1" Mounting Plates (MRV 34-frame motors)	_	4415-9031	-	-	3415-9057	_	



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### **MEXICO**

### Centro de Servicio

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