

# **ServoWeld** Actuators SWA & SWB MODELS



### ServoWeld SWA & SWB

Tolomatic is the world's leading manufacturer of integrated servo actuators for resistance spot welding, used by the world's top weld gun OEM's and numerous global vehicle manufacturers.

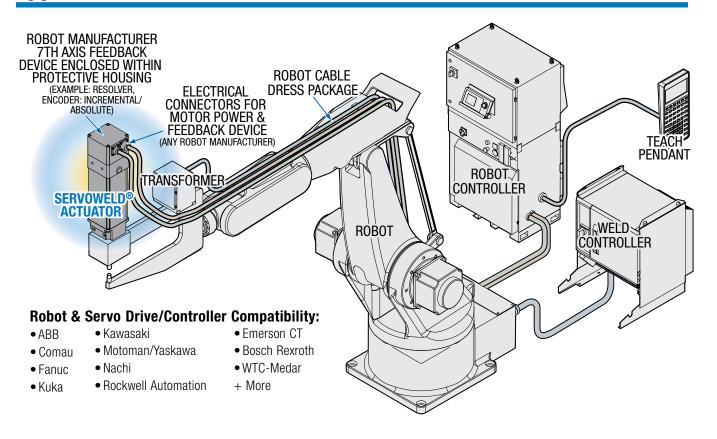
#### **Superior Integrated Servo Motor Actuators**

Tolomatic's ServoWeld family of integrated servo actuators are designed for best-in-class performance with the factors that are most important for resistance spot welding gun applications.

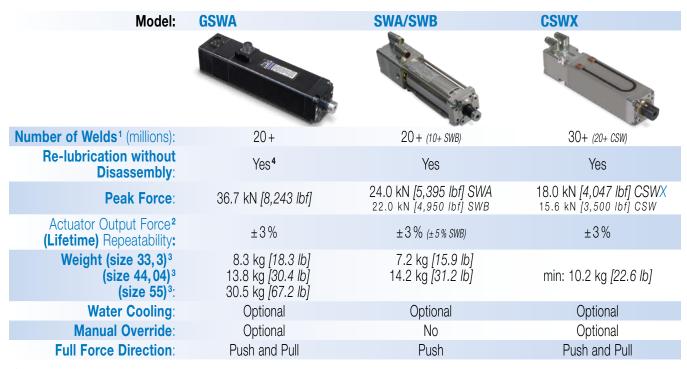
NUMBER OF WELDS/ PRODUCT LIFE	Tolomatic's superior roller screw design has the <u>highest dynamic load rating for more welds</u> than any competitive technology (other roller screws, ball screw, pneumatic).
FORCE REPEATABILITY	Skewed winding designed for welding minimizes motor cogging and <b>provides industry best actuator force repeatability:</b> • ±3 % Over the Lifetime of the Actuator
EFFICIENCY	All elements of actuator (winding, screw, rod scraper, bearings) are designed to optimize the efficiency of the actuator system and provide the <b>most energy efficient solution on the market.</b>
WELDS/ MINUTE	All elements of the actuator (winding, screw, rod scraper, bearings) are designed to last and run as cool as possible in welding applications, with the ability to add water cooling as an option. This means <b>more welds per minute than any competitive technology</b> (other roller screws, ball screw, pneumatic).
WEIGHT	Tolomatic integrated servo actuators minimize weight when designed into the weldgun. Additionally, Tolomatic can customize actuators for a specific weldgun applications to provide <b>industry leading light weight designs.</b>
LIFETIME COST	By building the longest lasting, most efficient and highest weld per minute actuators on the market, Tolomatic actuators provide the <b>lowest total cost per spot weld.</b>



## LDA belgium



# **Tolomatic Offers the Broadest, Most Capable Family of Integrated Servo Actuators for Resistance Spot Welding**



<sup>&</sup>lt;sup>1</sup> Based on properly lubricated ServoWeld unit used as recommended in user manual. Weld schedule, tip force, environment and lubrication are factors in the total number of welds achievable with ServoWeld actuators.



<sup>&</sup>lt;sup>2</sup> At weld force <sup>3</sup> Weight varies with choice of feedback device and mounting options

<sup>&</sup>lt;sup>4</sup> Some exceptions, see GSWA user manual

# SWA & SWB INTEGRATED MOTOR ACTOATORSIUM

## ENDURANCE TECHNOLOGY

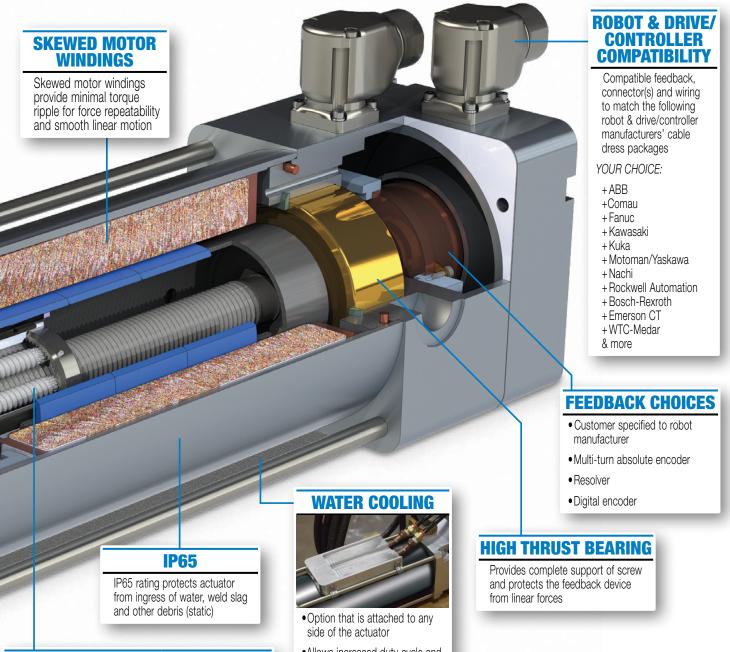
A Tolomatic Design Principle

Endurance Technology features are designed for maximum durability to provide extended service life.

#### **MULTIPLE MOTOR** WINDINGS YOU CAN CHOOSE: •460VAC or 230VAC rated windings potted directly into actuator housing **ROBUST BUSHINGS** • Integral thermal switch for over temperature protection Supports the **WATER SLOTS** thrust tube and nut assembly Allows for water to through entire flow away from thrust stroke length rod to prevent ingress into the actuator **THRUST TUBE** •Steel thrust tube supports extremely high force capabilities •Salt bath nitride treatment **GREASE PORT** provides excellent corrosion resistance, surface hardness and •Screw re-lubrication is very resistant to adherence system provides of weld slag, water and other extended screw life potential contaminants Convenient lubrication without disassembly 11111 **INTERNAL ROD WIPER THREADED** WITH SCRAPER **BUMPERS UNIVERSAL MOUNTING ROD END** Prevents contaminants Bumpers protect Tapped holes in front face allow for • Zinc plated steel the screw and from entering the mounting in any orientation... construction for actuator for extended life nut assembly 0°, 90°, 180° or 270° corrosion resistance from damage at end of stroke Provides a common

interface to multiple rod end options

# Tolomatic ... MAXIMUM-PARABELETUM



#### **ADVANCED SCREW TECHNOLOGY**

- Roller screws provide the highest thrust and life ratings available
- SWA: Highest DLR roller screw provides longest life
- SWB: Lower DLR roller screw, provides longer life than ball screws or inverted roller screws

•Allows increased duty cycle and increased jobs/hour

#### **OPTIONS**

BRAKE WATER COOLING REAR TRUNNION MOUNTING



# ServoWeld SWA & SWB - Integrated Motor Actuato Pelgium

**Table 1: Performance & Mechanical Specifications:** 

	SERIES	SERIES SWA3 or SWB3			SWA4 or SWB4										
FRAME	mm		90.0						110.0						
SIZE	in		3.54			4.33									
MOTOR W	INDING		A3 / B3		A2 /	B2		A3	/ B3			A4	/ B4		
NUT/	SCREW	RN04	RN05	RN10	RN05	RN10	RN04	RN05	RN05XR	RN10	RN04	RN05	RN05XR	RN10	
§ SCREW LEAD	mm	4.0	5.0	10.0	5.0	10.0	4.0	5.0	5.0	10.0	4.0	5.0	5.0	10.0	
PEAK	kN	11.1	11.1	5.8	14.5 / 12.8	7.3 / 6.4	17.8	14.7	22.1	11.1	17.8	14.7	24.0	17.8	
FORCE	lbf	2500	2500	1306	3261/2882	1630/1441	4000	3300	4958	2500	4000	3300	5395	4000	
MAX.	mm/sec	234	292	584	292	584	234	292	292	584	234	292	292	584	
VELOCITY	in/sec	9.2	11.5	23.0	11.5	23.0	9.2	11.5	11.5	23.0	9.2	11.5	11.5	23.0	
SWA SCREW DLR	kN	41.1	53.6	47.2	73.3	76.4	67.2	73.3	91.74	76.4	67.2	73.3	91.7	76.4	
(DYNAMIC LOAD RATING)	lbf	9240	12050	10611	16479	17175	15107	16479	20624	17175	15107	16479	20624	17175	
SWB SCREW DLR	kN	24.25	31.63	27.85	43.25	45.07	39.65	43.25	_	45.07	39.65	43.25	_	45.07	
(DYNAMIC LOAD RATING)	lbf	5452	7110	6260	9723	10133	8913	9723	_	10133	8913	9723	_	10133	
NOMINAL BACK	N	436	347	173	405	205	507	405	405	205	507	405	405	205	
DRIVE Force	lbf	98	78	39	91	46	114	91	91	46	114	91	91	46	
WEIGHT*	kg	7.80	7.80	7.80	11.25	11.25	12.29	12.29	12.29	12.29	14.16	14.16	14.16	14.16	
WEIGHT	lbf	17.2	17.2	17.2	24.8	24.8	27.1	27.1	27.1	27.1	31.2	31.2	31.2	31.2	
STROKE	mm	150	150	150	150	150	150	150	150	150	150	150	150	150	
JIIIOKE	in	6	6	6	6	6	6	6	6	6	6	6	6	6	
BASE	kg-cm <sup>2</sup>	4.8997	4.8997	4.8997	8.1108	8.1108	9.7864	9.7864	9.7864	9.7864	11.4073	11.4073	11.4073	11.4073	
INERTIA	lb-in	1.6723	1.6723	1.6723	2.7716	2.7716	3.3442	3.3442	3.3442	3.3442	3.8966	3.8966	3.8966	3.8966	
AMBIENT TEMP **	°C		_				C	to 50							
RANGE	°F							2 to 122							
IP RATING						Stan	dard IP65	5 (static)							
AGENCY LISTINGS		C € cULus AB													

<sup>\*</sup>Weight varies per feedback device or mounting option. See table below for details.

<sup>\*\*</sup>From 0-10°C (32-50°F), additional startup procedure may be required for optimal performance. See user manual for details. §NOTE: Screw/Lead Accuracy: 0.023 mm/300 mm; 0.0009 in/ft

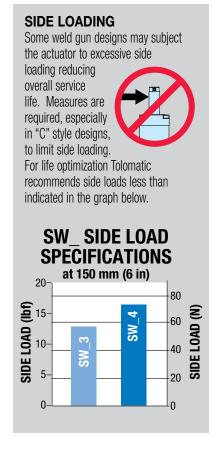
Table	ე.									
Iable	۷.	Weight Adder								
		Water	Rear		FE	EDBACK OP	TION			
		Cooling	Trunnion	F1	F2	A1	K1***	W1		
SW 3	kg	0.36	0.10	0.3	0.77	0.59	1.27	1.03		
SW_3	lb	0.80	0.22	0.65	1.70	1.30	2.80	2.26		
SW 4	kg	0.52	0.24	0.3	0.48	0.64	1.34	0.72		
3VV_4	lb	1.15	0.52	0.65	1.05	1.41	2.96	1.59		

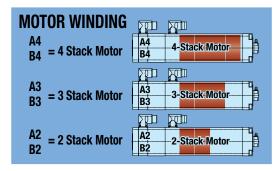
<sup>\*\*\*</sup>Weight adder for K1 option includes weight of brake

# ServoWeld SWA & SWB - Integrated Motor Actuator elgium

**Table 3: Motor Specifications:** 

		SW	<b>_3</b>	_3 SW_4						
	А3	В3	A2	B2	<b>A</b> 3	В3	A4	B4		
TORQUE CON	N-m/A Peak	0.62	1.21	0.52	0.90	0.61	1.20	0.64	1.29	
TORQUE CON	ISTANT (Kt)	in-lb/A Peak	5.5	10.7	4.6	8.0	5.4	10.6	5.7	11.4
VOLTAGE CON	STANT (K <sub>e</sub> )	V/Krpm Peak	79.8	154	66.1	107.2	78.1	153.1	81.1	162.3
	No Water	N-m	4.4	4.3	5.5	4.9	8.4	8.5	14.6	14.6
CONTINUOUS	Cooling	in-lb	39	38	48.8	43.0	74	75	129	129
STALL TORQUE	With Water	N-m	8.8	8.6	11.0	9.7	16.7	17.0	20.8	20.8
	Cooling	in-lb	78	76	97.6	86	148	150	184	184
CONTINUOUS	No Water Cooling	$A_{\scriptscriptstyle RMS}$	5	2.5	7.5	3.8	9.7	5.0	16	8
STALL CURRENT	With Water Cooling	$A_{RMS}$	10.0	5.0	15.0	7.6	19.4	10.0	23	12
DE	AK TORQUE	N-m	13.2	12.9	16.5	14.6	25.1	25.4	43.7	43.7
rc	AK TUNQUE	in-lb	117	114	146	129	222	225	387	387
PEA	K CURRENT	$A_{RMS}$	15	7.5	22.5	11.4	29.1	15.0	48	24
R	ESISTANCE	Ohms	2.07	8.3	0.9	4.2	0.58	2.32	0.36	1.46
INDUCTANCE			3.8	15	3.65	15.7	2.75	11.5	2.04	8.9
NO. OF POLES						8	3			
BL	JS VOLTAGE	$V_{\scriptscriptstyle RMS}$	230	460	230	460	230	460	230	460
SPEED	@ RATED V	RPM	3,500							





#### **Table 4: Brake Specifications:**

	SERIES	SW_3	SW_4
ROTOR	gm-cm <sup>2</sup>	73	239
INERTIA	oz-in²	0.400	1.307
CURRENT	Amp	0.43	0.67
HOLDING	N-m	4.0	10.0
TORQUE	in-lb	35	89
ENGAGE TIME	mSec	40	25
DISENGAGE TIME	mSec	50	50
VOLTAGE	Vdc	24	24

#### **BRAKE CONSIDERATIONS**

In all vertical application an un-powered SWA will require a brake to maintain position. Tolomatic recommends that the nominal

back drive force specification (listed in Table 1) be used for reference only. Back drive force is subject to change throughout the life of the actuator, due to mechanical break in, ambient temperature, and duty cycle variation.

A brake can be used with the actuator to keep it from backdriving, typically in vertical applications. A brake may be used for safety reasons or for energy savings allowing the actuator to hold position when un-powered.

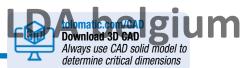
Brake w

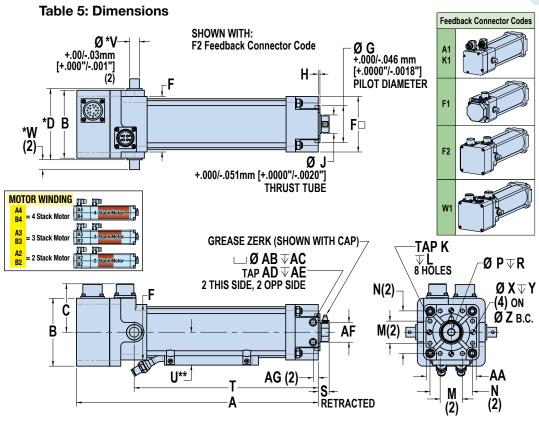
NOTE: The optional Spring-Applied / Electronically-Released Brake requires 24V power.



Brake will increase actuator length and weight, see Table 2 (K1).

### **SWA & SWB Dimensions**





	SW_3	SW_4				
F	90.0	110.0				
G	60.000	64.500				
Н	2.8	3.4				
J	30.135	34.926				
K	M8 x 1.25	M8 x 1.25				
L	16.0	13.0				
M	36.0	29.072				
N	69.0	79.874				
P	M12 x 1.25	M20 x 1.5				
R	22.2	25.9				
S	17.6	19.1				
T	273.0	321.0				
U**	53.3	66.7				
٧*	15.98	20.0				
W*	16.0	20.1				
X	_	8.052/8.026				
Y	ı	12.7				
Z	_	85.00				
AA	_	94.01/93.95				
AB	_	12.09/12.04				
AC	-	6.00				
AD	_	M10 x 1.5				
AE	_	16.00				
AF	_	50.00				
AG	_	15.00				

\*for Trunnion Option \*\*for Water Cooling Option Dimensions in millimeters

					SW_3					SW_4		
Motor Winding	Feedb	ack	<b>A1</b>	F1	F2	K1	W1	A1	F1	F2	K1	W1
A,B 2,3	w/o Brake		350.5	343.5	366.5	**	387.3	402.9	395.4	418.0	**	439.3
A,B 2,3	w/ Brake	A	373.9	375.5	**	377.7	401.6	427.1	433.9	**	422.2	453.5
A,B 4	w/o Brake	A	ı	ı	-	_	-	410.7	403.2	425.8	**	447.1
A,B 4	w/ Brake		1	-	_	_	_	434.9	441.7	**	423.3	461.3
		В	90.0	90.0	110.0	90.0	110.0	110.0	110.0	110.0	110.0	110.0
		C	85.3	71.6	78.4	86.4	78.0	94.1	78.4	78.4	96.4	78.0
		D*	95.2	95.2	123.0	95.2	123.0	123.0	123.0	123.0	123.0	123.0
	ck Connector de/Type	•	A1 SWIVEL	F1 BOX	F2 BOX	K1 SWIVEL	W1 BOX	A1 SWIVEL	F1 BOX	F2 BOX	K1 SWIVEL	W1 BOX

*for Trunnion Option	**Contact	Tolomatic for	r additional information	Dimensior	ns in millimeters
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					SW_3					SW_4		
Motor Winding	Feedb	ack	<b>A</b> 1	F1	F2	K1	W1	A1	F1	F2	K1	W1
A,B 2,3	w/o Brake		13.80	13.52	14.43	**	15.25	15.86	15.57	16.46	**	17.29
A,B 2,3	w/ Brake		14.72	14.78	**	14.87	15.81	16.81	17.08	**	16.62	17.85
A,B 4	w/o Brake	А	_	-	_	_	_	16.17	15.8 7	16.76	**	17.60
A,B 4	w/ Brake		1	1	-	_	-	17.12	17.39	**	16.67	18.16
		В	3.54	3.54	4.33	3.54	4.33	4.33	4.33	4.33	4.33	4.33
		C	3.36	2.82	3.09	3.40	3.07	3.71	3.09	3.09	3.80	3.07
		D*	3.75	3.75	4.84	3.75	4.84	4.84	4.84	4.84	4.84	4.84
	ack Connecto ode/Type	r	A1 SWIVEL	F1 BOX	F2 BOX	K1 SWIVEL	W1 BOX	A1 SWIVEL	F1 BOX	F2 BOX	K1 SWIVEL	W1 BOX

\*for Trunnion Option \*\*Contact Tolomatic for additional information Dimensions in inches

	SW_3	SW_4
F	3.54	4.33
G	2.3622	2.5394
Н	0.11	0.13
J	1.1864	1.3750
K	M8 x 1.25	M8 x 1.25
L	0.63	0.51
M	1.42	1.1446
N	2.72	3.1446
Р	M12 x 1.25	M20 x 1.5
R	0.88	1.02
S	0.69	0.75
T	10.75	12.64
U**	2.10	2.63
٧*	0.629	0.787
W*	0.63	0.79
X	I	0.3170/0.3160
Y	-	0.50
Z	ı	3.346
AA	_	3.701/3.699
AB	-	0.476/0.474
AC	_	0.236
AD	_	M10 x 1.5
AE	_	0.630
AF	-	1.969
AG	_	0.591

\*for Trunnion Option \*\*for Water Cooling Option Dimensions in inches



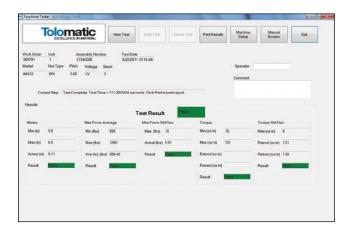
## Complete Verification Testing is Performed on Every Actuator um

#### EVERY SERVOWELD ACTUATOR HAS TO PASS RIGOROUS TESTING AT OUR FACTORY.

We verify the performance of each individual unit before delivery to ensure they conform to Tolomatic's high standard of performance.



Functional unit testing for hundreds of cycles quantifies stroke, length, torque under no load, input current vs force standard deviation.



Testing parameter results in progress for the Functional Test procedure.



Final system test ensures the feedback device is properly aligned with the ServoWeld motor poles.

## 1. High POT (High Potential/High Voltage Test)

This standard electric motor test procedure is a 3-part test that checks the insulation system of the assembly to verify proper armature and thermal wire insulation.

# 2. Electronic phasing of ServoWeld® and feedback device (Encoder, Resolver, Feedback Device)

Using a fixed current and a specially designed fixture the feedback device is physically and electronically aligned relative to the phasing of the Tolomatic motor.

#### 3. Functional Testing

Performed with Tolomatic motion control components and dedicated data acquisition equipment. Operated for hundred of cycles, this test quantifies these parameters - stroke length, torque under no load, input current vs force average, input current vs force standard deviation - using an electronic load cell in conjunction with data acquisition equipment.

#### 4. Tolomatic System Test

Using a single-axis control unit the test ensures that the feedback device is properly aligned with the poles of the Tolomatic motor.

### **ServoWeld Application Guidelines**

## LDA belgium

**SIDE LOADING:** Weld gun designs may subject the actuator to excessive side loading, reducing overall service life. The GSWA33 and CSW(x) Guided actuators will accommodate side loading caused by the mass of the electrode, misaligned weld tips and tip skid. For other ServoWeld configurations additional measures are required to limit side loading, especially in "C" style gun designs. For maximum service life, external guiding is recommended to minimize side loading to the thrust rod and provide consist weld gun alignment throughout the service life. Reference the side load capacity charts in the GSWA, SWA/SWB, and CSW(x) manuals and/or brochures.

**THRUST ROD WIPER/SCRAPER:** For maximum service life, measures should be taken to reduce/eliminate contamination, weld slag, and water in the thrust rod wiper/scraper interface area. Implementation of industrial thrust rod boot and/or deflective device can be effectively utilized in this area.

**CABLES:** Shielded power & feedback cables are recommended to minimize electrical noise/grounding issues. Electrical noise or inadequate grounding can corrupt the feedback device signal.

**RSW SERVO SYSTEM CALIBRATION:** RSW weld gun servo system consists of robot 7th axis amplifier, robot feedback device, robot RSW software, weld gun chassis, & ServoWeld.

For optimal RSW weld gun servo system performance the calibration process should include maximum weld tip force from the production weld schedule, tip dress force, and multiple weld tip forces in-between. Utilizing all the available robot manufacturer force table inputs will provide best RSW weld gun servo system performance. The same weld tip part contact speed should be used for both RSW weld gun servo system calibration and production weld schedule.

**WELD TIP/PART CONTACT SPEED**: Tolomatic testing confirms the highest ServoWeld repeatability (**INPUT** 

**CURRENT** verses **OUTPUT FORCE**) at a weld tip part contact speed of 25mm/second or less. Speeds greater than 25mm/second can create "impact contribution" to the weld force. This impact contribution to the weld force deteriorates prior to completion of the weld cycle.

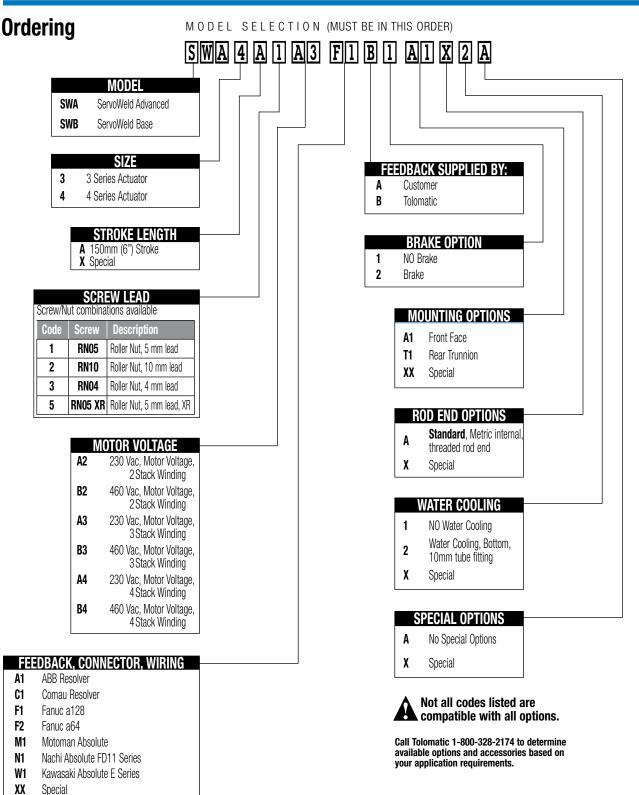
**ROBOT CARRIED APPLICATIONS:** Robot carried RSW gun applications have reduced exposure to water pooling/water ingression by virtue of the continuous robot movement and various RSW gun positions. In addition, in robot carried applications positioning of the RSW gun can be programmed as part of the weld cap change program/routine to eliminate ServoWeld exposure to water. (ServoWeld above weld caps)

ROBOT MANUFACTURER SERVO FILE: Robot manufacturer servo parameter files for operation of ServoWeld are available only from the robot manufacturer. Each robot manufacturer creates 3rd party motor servo parameter files, validates operation of ServoWeld via their 7th axis, and maintains servo motor parameter file for operation of ServoWeld.

**TOOL CHANGER APPLICATIONS:** Weld gun storage fixture in cell should position weld gun so movable electrode is not loading ServoWeld thrust rod - back driving the ServoWeld. Weld gun tips should be positioned to weld gun closed at low force prior to disconnect from robot/tool changer. Consider ServoWeld configured with integral brake option.

FIXED/PEDESTAL APPLICATIONS: One of the more challenging RSW applications is a pedestal RSW gun, ServoWeld mounted vertical – thrust rod up. Measures should be taken to reduce and/or eliminate the ServoWeld to water exposure, water pooling/spray in the access areas of the ServoWeld unit to maximize overall service life.

# ServoWeld SWA & SWB Integrated Motor Actuators elgium



# The Tolomatic Difference Expect More From the Industry Leader:



#### INNOVATIVE **PRODUCTS**

Solutions with Endurance Technology<sup>SM</sup> for challenging applications.



Built-to-order with configurable stroke lengths and flexible mounting options.



### SIZING

Size and select electric actuators with our online software.



### **HERE®**

Match your motor to compatible mounting plates with Tolomatic actuators.



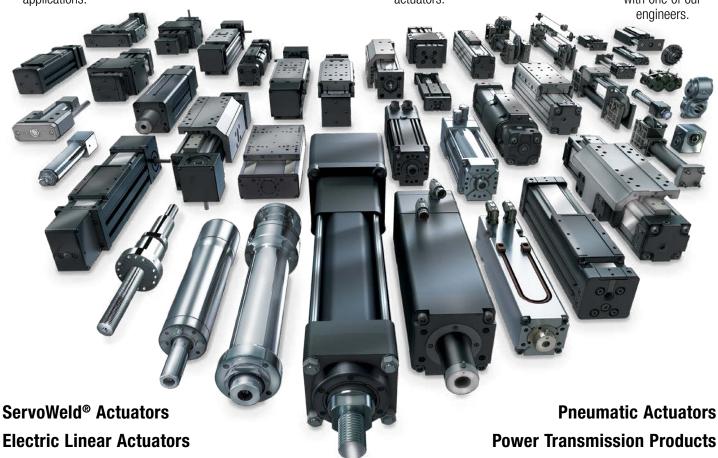
### LIBRARY

Download 2D or 3D CAD files for Tolomatic products.



#### TECHNICAL SUPPORT

Get a question answered or request a virtual design consultation with one of our





### **Toloma**t **EXCELLENCE IN MOTION**

**COMPANY WITH** QUALITY SYSTEM **CERTIFIED BY DNV** = ISO 9001 = Certified site: Hamel, MN

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